As defined in its Terms of Reference, the European UAS Standards Coordination Group (EUSCG) is a joint coordination and advisory group established to coordinate the standardisation activities related to Unmanned Aircraft Systems. The Rolling Development Plan (RDP) is periodically updated to reflect the current situation. It may therefore not be exhaustive in some areas. Its contents should be used for information purposes only and should not be used as any regulatory reference.

Standards related to Cyber Security are covered by the European Cyber security for aviation Standards Coordination Group (ECSCG). The ECSCG RDP is available at www.ecscg.eu

Standards related to ATM are covered by the European ATM Standards Coordination Group (EASCG). The EASCG RDP is available at www.eascg.eu"

Information about EUSCG SDO documents

	Test method - a definitive procedure that produces a test result.
	Guide - information or series of options that does not recommend a specific
	course of action.
	Practice - a definitive set of instructions for performing one or more specific
	operations that does not produce a test result.
ASTM	Classification - a systematic arrangement or division of materials, products,
	systems, or services into groups based on similar characteristics such as
	origin, composition, properties, or use.
	Terminology - a document comprising definitions of terms; explanations of
	symbols, abbreviations, or acronyms.
	•
	Minimum Aviation Systems Performance Standards (MASPS) - describes and specifies the operational and/or functional requirements of a complete
	end-to-end system, which may include airborne, on-ground and space
	segments. It should provide a high-level architecture describing the individual
	components, and should allocate between those components the
	performance, safety and interoperability requirements.
	Operational Services and Environment Definition (OSED) - a document
	dedicated to the operational concept description: it provides the definition of
	the considered services and of the environment, in which they have to be
	provided. It is usually published as an annex to the SPR.
	Safety and Performance Requirements Standard (SPR) - a standalone
	document dedicated to operational safety and performance issues: it provides
	an allocation of the requirements between the segments for the different
	approval types.
	Interoperability requirements standard (INTEROP) - a standalone
	document dedicated to interoperability issues between the different segments:
EUROCAE	for each of them, it identifies the technical interface and related functional
	requirements
	Process Standard - specifies generic methods, which are not specific to
	individual components, e.g. software or hardware development,
	environmental testing
	Minimum Operational Performance Standard (MOPS) - specifies the
	performance of a component (piece of equipment, protocols, exchange
	formats,), which is the minimum necessary performance to satisfy a
	regulatory requirement. In particular, it specifies the tests to be made to ensure
	that the specified performance is achieved.
	Technical Standard - specifies performance of a component, which reflects
	the best industrial practice.
	Guidance Document - supplements the information contained in the types of documents described above. Usually illustrative information to another
	EUROCAE document.
	Internal Report - represents the opinion of a WG on a certain technical topic.
	It is identified with a WG reference number and date only.
1	The lacitation with a WO reference number and date only.

	Specifications - Define technical and/or operational procedures that advance ATM
	Guidelines - Provide more general implementation support to stakeholders.
EUROCONTROL	NOTE: Standards are developed and maintained as both harmonising
LUNGCONTROL	standards and as means of compliance. Standards are used as reference
	material by ICAO and EASA, and continue to provide the basis of
	Community Specifications for the extant EU SES regulations in accordance
	with regulation EC 552/2004 (Interoperability Regulation).
	International Standard - provides rules, guidelines or characteristics for
	activities or for their results, aimed at achieving the optimum degree of order
	in a given context. It can take many forms. Apart from product standards,
	other examples include: test methods, codes of practice, guideline
	standards and management systems standards.
	Technical Specification - addresses work still under technical development,
	or where it is believed that there will be a future, but not immediate,
	possibility of agreement on an International Standard. A Technical
	Specification is published for immediate use, but it also provides a means to
	obtain feedback. The aim is that it will eventually be transformed and
	republished as an International Standard.
	Technical Report - contains information of a different kind from that of the
	previous two publications. It may include data obtained from a survey, for
	example, or from an informative report, or information of the perceived " state
	of the art ".
	Publicly Available Specification - is published to respond to an urgent
ISO	market need, representing either the consensus of the experts within a
100	working group, or a consensus in an organization external to ISO. As with
	Technical Specifications, Publicly Available Specifications are published for
	immediate use and also serve as a means to obtain feedback for an eventual
	transformation into an International Standard. Publicly Available
	Specifications have a maximum life of six years, after which they can be
	transformed into an International Standard or withdrawn.
	International Workshop Agreement - is a document developed outside the
	normal ISO committee system to enable market players to negotiate in an "
	open workshop "environment. International Workshop Agreements are
	typically administratively supported by a member body. The published
	agreement includes an indication of the participating organizations involved
	in its development. An International Workshop Agreement has a maximum
	lifespan of six years, after which it can be either transformed into another
	ISO deliverable or is automatically withdrawn.
	Guides - help readers understand more about the main areas where
	standards add value. Some Guides talk about how, and why, ISO standards
	can make it work better, safer, and more efficiently.
	Standards - these Technical Reports are a documentation of broadly
	accepted engineering practices or specifications for a material, product,
	process, procedure or test method.
	Recommended Practices - these Technical Reports are documentations of
	practice, procedures and technology that are intended as guides to standard
	engineering practice. Their content may be of a more general nature, or they
SAE	may propound data that have not yet gained broad acceptance.
JAE	Information Reports - these Technical Reports are compilations of
	engineering reference data or educational material useful to the technical
	community.
	Aerospace Material Specifications - these Technical Reports identify
	material and process specifications conforming to sound, established
	engineering and metallurgical practices in aerospace sciences and practices.

Change A=added D=deleted M=modified	Domains	Regulatory activity	Content of the Regulation	Regulatory organisation	Target date for regulatory material publication	EASA UAS categories	Status	Standardisation activity	Short description of the deliverable	SDO	Target date for publication	Type of document (standard, supporting material etc.)	Status	Comments
1								Ger	neral					
	Manuals	EU 2019/945	Part 6(4), direct remote identification add-on shall be placed on the market with a user's manual providing the reference of the transmission protocol used for the direct remote identification emission and the instruction to: (a) install the module on the UA; (b) upload the UAS operator registration number.	EASA	Jun-19	open	Regulation applicable	prEN4709-2 Aerospace series - Unmanned Aircraft Systems (UAS). Security Requirements	This European standard will provide means of compliance to cover Part 6 and the relevant requirements from part 2 to 4 of the delegated act. DIRECT REMOTE IDENTIFICATION shall comply with the following: Ensure, in real time during the whole duration of the flight of the UA to which it is attached, the direct periodic broadcast, using an open and documented transmission protocol, of the following data in a way that they can be received directly by existing mobile devices within the broadcasting range: (a) the UAS operator registration number; (b) the physical serial number of the add-on compliant with standard ANSICTA-2063; (c) the geographical position of the UA, its height above the take-off point and associated date and time; (d) the direction and speedof the UA; and (e) the geographical position of the UA pilot (or if not available (class 1), the take-off point	ASD-STAN D5WG8	Sep-21	preEN / European standard	published	
	Manuals	EU 2019/945	Part 5(4), UAS in class C4 shall be placed on the market with a user's manual providing: (a) the characteristics of the UA including but not limited to the: — class of the UA — UA mass (with a description of the reference configuration) and the maximum take-off mass (MTOM); — general characteristics of allowed payloads in terms of mass dimensions, interfaces with the UA and other possible restrictions; — equipment and software to control the UA remotely; — and a description of the behaviour of the UA in case of a loss of data link; (b) clear operational instructions; (c) maintenance instructions; (e) operational ilmitations (including but not limited to meteorological conditions and daylinght operations); and (f) appropriate description of all the risks related to UAS operations;	EAGA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class CO, C1, C2, C3 and C4 UAS). This document does not over "specific" or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammabilly, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
	Manuals	EU 2019/945	Part 2(18), 3(19) and 4(15) UAS in class C1, C2 and C3 shall be placed on the market with a user's manual provising: (a) the characteristics of the UA including but not limited to the: —lass of the UA; —UA mass (with a description of the reference configuration) and the maximum take-off mass (MTOM); —general characteristics of allowed payloads in terms of mass dimensions, interfaces of with the UA and other possible restrictions; —equipment and software to control the UA remotely; —reference of the transmission protocol used for the direct remote identification emission; —sound power level; —and a description of the behaviour of the UA in case of a loss of data link; (b) clear operational instructions; (c) procedure to upload the airspace limitations; (d) maintenance instructions; (e) iroubleshooting procedures; (f) operational imitations (including but not limited to meteorological conditions and daylnight operations); and (g) appropriate description of all the risks related to UAS operations;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmannel Aurtraft Systems (UAS). Product and Verification Requirements	This document does not cover "Specific" or "Certified" category of UAS. Compliance with this document assists in complying with CE marking	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
2								UAS Traffic	Management					
	Remote E-identification	EU 2019/945	Part 2(12), 3(14) and 4(9) UAS in class C1, C2 and C3 shall hhave a direct remote identification that: (a) allows the upload of the UAS operator registration number in accordance with Article 14 of Implementing Regulation (EU) [20190517-120] and exclusively following the process provided by the registration system; (b) ensures, in real time during the whole duration of the flight, the direct periodic broadcast from the UA using an open and documented transmission protocol, of the following data, in a way that they can be received directly by existing mobile devices within the broadcasting range: I the UAS operator registration number; if the unique physical serial number of the UA compliant with standard ANSUCTA-2053; if the goographical position of the UA and its height above the surface or take-off point; iv the route course measured clockwise from true north and ground speed of the UA, and v the geographical position of the remote pilot; (c) ensures that the user cannot modify the data mentioned under paragraph (b) points it, iii, iv and the prographical proprists iii, iii, very propriets and the prographical proprists iii, iii, very propriets and the prographical proprists iii, iii very prographical proprists iiii, iii very prographical proprists iiii, iii very propriets iiii.	EASA	Jun-19	open category and specific	Regulation applicable	prEN4709-2 Aerospace aeries - Unmanned Aircraft Systems (UAS) - Security Requirements	This European standard will provide means of compliance to cover Part 6 and the relevant requirements from part 2 to 4 of the delegated act. DIRECT REMOTE IDENTIFICATION shall comply with the following: Ensure, in real time during the whole duration of the flight of the UA to which it is attached, the direct periodic broadcast, using an open and documented transmission protocol, of the following data in a way that they can be received directly by existing mobile devices within the broadcasting range: (a) the UAS operator registration number; (b) the physical serial number of the add-on compliant with standard ANSICTA-2051; (c) the geographical position of the UA, its height above the take-off point and associated date and time; (d) the direction and speedof the UA; and (e) the geographical position of the UA pilot (or if not available (class 1), the take-off point	ASD-STAN D5WG8	Sep-21	preEN / European standard	Published	

Remote E- identification	EU 2019/945	Part 6(1, 3 and 4) A direct remote identification add-on shall comply with the following: (1) allows the upload of the UAS operator registration number in accordance with Article 14 of Implementing Regulation (EU) [20190517-120] and exclusively following the process provided by the registration system; (3) ensures, in real time during the whole duration of the flight, the direct periodic broadcast from the UA using an open and documented transmission protocol, of the following data, in a way that they can be received directly by existing mobile devices within the broadcasting range; it he unique physical serial number; ii the unique physical serial number of the add-on compliant with standard ANSUCTA-2053; iii the goographical position of the UA and its height above the surface or take-off point; with eroute course measured clockwise from true north and ground speed of the UA, and v the goographical position of the remote pilot or, if not available, the take-off point; (4) ensures that the user cannot modify the data mentioned under paragraph (3) points ii, iii, iv and v;	EASA	Jun-19	open category and specific	Regulation applicable	prEN4709-2 Aerospace series - Unmanned Aircraft Systems (UAS) - Security Requirements	This European standard will provide means of compliance to cover Part 6 and the relevant requirements from part 2 to 4 of the delegated act. DIRECT REMOTE IDENTIFICATION shall comply with the following: Ensure, in real time during the whole duration of the flight of the UA to which it is attached, the direct periodic broadcast, using an open and documented transmission protocol, of the following data in a way that they can be received directly by existing mobile devices within the broadcasting range: (a) the UAS operator registration number; (b) the physical serial number of the add-on compliant with standard ANSICTA-2063) position of the UA, its height above the take-off point and associated date and time; (d) the direction and speedoff the UA; and (e) the geographical position of the UA pilot (or if not available (class 1), the take-off point	ASD-STAN D5WG8	Sep-21	preEN / European standard	Published	
Marking and Registration	EU 2019/947	Art 14(8) The UAS operators shall display their registration number on every unmanned aircraft meeting the conditions described in paragraph 5	EASA	Jun-19	Open category and Specific	Regulation applicable from 1 July 2020							
Marking and Registration							ASTM F2851-18 Standard Practice for UAS Registration and Marking (Excluding Smal Unmanned Aircraft Systems)	This practice follows ICAO Annex 7 SARPS except in areas where the unique aspects of UAS may not allow compliance. In these cases, this document will address the issue and recommend the need for an alternate compliance method.	ASTM F38 Unmanned Aircraft Systems		standard	published	Renewed 2018
Geo-awarenes:	EU 2019/945	Part 2(13), 3(15) and 4(10) UAS in class C1, C2 and C3 shall be equipped with a geo-awareness system that provides: (a) an interface to load and update data containing information on airspace limitations related to UA position and altitude imposed by the geographical zones, as defined by Article 15 of Implementing Regulation (EU) (20190517-120), which ensures that the process of loading or updating such data does not degrade is integrity and validity; (b) a warning alert to the remote pilot when a potential breach of airspace limitations is detected; and (c) information to the remote pilot on the UA's status as well as a warning alert when its positioning or navigation systems cannot ensure the proper functioning of the geo-awareness system	EASA	Jun-19	Open category and Specific	Regulation applicable	prEN4709-3 Aerospace series - Unmanned Aircraft Systems (UAS) - Security Requirements	This European standard will provide means of compliance to cover geo- awareness related requirements for Part 2 to 4 of the delegated act. More specifically, the standard will provide requirements related to the main characteristics of the geo-awareness function, namely. An interface to load and update data containing information on airspace limitations which ensures that the process of loading or updating of this data does not departed is integrity and validity. A warning alert to the pilot when a potential breach of airspace limitations is detected 'Information to the pilot on the UA's status as well as a warning alert when its positioning or navigation cannot ensure the proper functioning of the geo- awareness system In the context of this standard, geo-awareness is defined as an UAS function that warns the remote pilot if the UA is going to enter into an unauthorized zone.	ASD-STAN D5WG8	Sep-21	preEN / European standard	Published	
Definition of zones	EU 2019/947	Article 15 Operational conditions for UAS geographical zones I when defining UAS geographical zones for safety, security, privacy or environmental reasons, Member States may (a) prohibit certain or all UAS perations, request particular conditions for certain or all UAS operations or request a prior operational authorisation for certain or all UAS operations (b) subject UAS operations to specified environmental standards; (c) allow access to certain UAS classes only; (d) allow access to entain UAS classes only (d) allow access only to UAS equipped with certain technical teatures, in particular remote identification systems or geo awareness systems. 2 On the basis of a risk assessment carried out by the competent authority, Member States may designate certain geographical zones in which UAS operations are evempt from one or more of the 'open' category requirements. 3 When pursuant to paragraphs 1 or 2 Member States define UAS geographical zones, for geo awareness purposes they shall ensure that the information on the UAS operations, including their period of validity, is made publicly available in a common unique digital format.	EASA	Jun-19	Open category and Specific	Regulation applicable from 1 July 2020							
U-space							MOPS for UAS Geo- Fencing	ED-269 "Minimum Operational Performance Standard for UAS geo-fencing" defining minimum requirements for the geo-fencing function at the level of individual components.	EUROCAE WG-105		standard	published	
U-Space							MOPS for UAS geo- caging	ED-270 "Minimum Operational Performance Standard for UAS geo-caging" defining minimum requirements for the geo-caging function at the level of individual components.	EUROCAE WG-105		standard	published	

	U-space	prEN4709-3 Aerospace series - Umanned Aircraft Systems (UAS) - Security Requirements	This European standard will provide means of compliance to cover geo- awareness related requirements for Part 2 to 4 of the delegated act. More specifically, the standard will provide requirements related to the main characteristics of the geo-awareness function, namely. - An interface to load and update data containing information on airspace limitations which ensures that the process of loading or updating of this data does not deparde its nitegrity and validity. - A warning alert to the pilot when a potential breach of airspace limitations is detected. - Information to the pilot on the UA is status as well as a warning alert when its positioning or navigation cannot ensure the proper functioning of the geo- awareness system in the context of this standard, geo-awareness is defined as an UAS function that warns the remote pilot if the UA is going to enter into an unauthorized zone. The standard will be developed in coordination with EUROCAEWG 105 / SG 33	ASD-STAN DSWG8	Sep-21	preEN / European standard	published	
		WK69690 Surveillance UTM Supplemental Data Service Provider (SDSP) Performance		ASTM F38		Standard	ongoing	
		ISO/WD 23629-5		ISO TC20 SC16	Nov-21	Standard	ongoing	
 		ISO/WD 23629-8 ISO/CD 23629-7	UTM — Part 8: Remote identification UTM – Part 7: Data model for spatial data	ISO TC20 SC16 ISO TC20 SC17	May-21 Jan-22	Standard Standard	ongoing	
		ISO/23629-12	UTM — Part 12: Requirements for UTM services and service providers	ISO TC20 SC18	Nov-22	Standard	ongoing	
		1-5/	-	EUROCAE WG-				
М	1	EUROCAE Document	MOPS for U-Space Geo-awareness Service	105 SG-3	Q2-2023	Standard	ongoing	
м		EUROCAE Document	MOPS for Traffic information / situation dissemination exchange format and	EUROCAE WG-	Q1-2024	Standard	ongoine	
· · ·		EUROCAE Document	service	105 SG-3	Q 1-2024	StariUali U	ongoing	
М	_	EUROCAE Document	MOPS for Flight Planning and Authorization Service for global awareness in	EUROCAE WG-	Q1-2024	Standard	ongoing	
			A/UTM in U-Space	105 SG-3		- Citariata G	ongonig	
M	1	EUROCAE Document	MOPS for Network Identification Service of unmanned aerial vehicles for A/UTM/U-Space	EUROCAE WG- 105 SG-3	Q4-2022	Standard	On hold	Way forward being defined
			Al O TIME O-Opace	100 00-0				The task is an update to the
		EUROCAE Document	Technical Specification for Geographical Zones and U-Space data provision and exchange	EUROCAE WG- 105 SG-3	Q2-2023	Standard	ongoing	previously proposed task called 'Minimum Operational Performance Standard for Aeronautical Data Provision and Exchange'; it is a new document but it is not a new activity under SG-3 (it is one of the 5 activities initially identified)
		WK75981 New Specification for Vertiport Automation Supplemental Data Service Provider (SDSP)	The objective is to define minimum performance-based standards for Vertiport Automation Supplemental Data Service Provider (SISP) data and services to UAS Service Suppliers/Providers (USS/USP). Operators in a UAS Traffic Management (UTM) and Provider of Services for UAM (PSU) ecosystem.	ASTM F38		Standard	ongoing	
М	Electronic Identification	F3411-22 Standard Specification for Remote ID and Tracking	Revision of standard to ensure compatibility with both European and North American regulation and provide a means of compliance for FAA.	ASTM F38.02	April-22	Standard	published	
		F3586-22 Practice for standard practice for Remote ID meansof Compliance to FAA regulation Part 89	Practice for standard practice for Remote ID means of Compliance to FAA regulation Part 89	ASTM F38.02	Jul-22	Standard	published	Only applicable for operations in US
		EUROCAE Document ED-102B	MOPS for ADS-B and TIS on 1090 MHz This document supersedes ED-102A and contains the following main changes: Addition of Phase Overtay Modulation Support for Flight Deck Interval Management Applications Improved Geometric Altitude Reporting Specification of a Position Message Format Algorithm Deletion of T-Bit Handling Transmission of Air and Pitot Weather Reports Transmission of Air and Pitot Weather Reports Support for UAS/RPAS Operations Support for UAS/RPAS Operations Support for Sub-orbital High-Velocity Operations It is technically identical to RTCA DO-260C. For the implementation of the Phase Overlay functionality, ED-102B refers to patented material from ACSS (Avisition Communication & Surveillance Systems, LLC), ACSS has granted a Commitment to License which is contained in the MOPS in Appendix K.	EUROCAE		standard	published	Standard added to RDP as it was recommended by AW-Drones
		ISO 23629-9	This document mainly specifies minimum requirements for elements of information exchange between UTMs ervice providers (USP) and different users to support relevant UTM services between them, while the protocol requirements and transmission requirements of UTM actors at the operational level are not included.	ISO/TC 20/SC 16		standard	ongoing	Added to RDP as standard was recommended by AW-Drones
3		Command, Control	and Communication					
	C3 datalink and		Minimum Operational Performance Standard for the satellite Command and	EUROCAE				Comment resolution
М	communication	ED-265	Control Data Link (C-Band Satellite)	WG-105	Q1-2024	standard	ongoing	

3 datalink and ommunication		ASTM F3002-14a Standard Specification for Design of the Command and Control System for Small Unmanned Aircraft Systems (sUAS)	This specification is provided as a consensus standard in support of an application to a nation's governing aviation authority (GAA) for a permit to operate a small unmanned aircraft system (sUAS) for commercial or public use purposes. This standard outlines the general, spectrum and link requirements for C2.	ASTM F38 Unmanned Aircraft Systems		standard	published	Under revision
3 datalink and ommunication		AIR6514 UxS Control Segment (UCS) Architecture: Interface Control Document (ICD)	This interface control document (ICD) specifies all software services in the Unmanned Systems (UkS) Control Segment Architecture, including interfaces, messages, and data model.	SAE AS-4UCS Unmanned Systems (UxS) Control Segment Architecture		information report	published	
3 datalink and mmunication		AIR6514A UxS Control Segment (UCS) Architecture: Interface Control Document (ICD)	This interface control document (ICD) specifies all software services in the Unmanned Systems (UxS) Control Segment Architecture, including interfaces, messages, and data model.	SAE AS-4UCS Unmanned Systems (UxS) Control Segment Architecture	Nov-18	information report	ongoing	
3 datalink and mmunication		AS6522A Unmanned Systems (UxS) Control Segment (UCS) Architecture: Architecture Technical Governance	The UCS technical governance comprises a set of policies, processes, and standard definitions to establish consistency and quality in the development of architecture artifacts and documents. It provides guidance for the use of adopted industry standards and modeling conventions in the use of Unified Modeling Language (UML) and Service Oriented Architecture Modeling Language (UML) and Service Oriented Architecture Modeling Language (UML) and where the UCS Architecture devates from normal UML conventions. This document identifies the defining policies, guidelines, and standards of technical governance in the following subjects: Industry standards adopted by the AS-4UCS Technical Committee. These are the industry standards and specifications adopted by AS-4UCS in the generation and documentation of the architecture UCS Architecture Development: UCS specific policies on the development of the UCS Architecture. The AS-4UCS Technical Committee governance policies are intentionally minimal. The object is to provide direction specific to the intent and scope of developing architecture artifacts that follow a consistent set of specifications and industry best practices. Standards are referenced within policies. Standards may place constraints on policies that a UML diagram be modeled in a particular methodology using only approved stereotypes from the SoaML UML profile. UCS technical governance applies to the following item: - UXS Control Segment (UCS) Architecture. The technical governance applies to the following item: - UXS Control Segment (UCS) Architecture: Technical Committee. It is not applicable to third party developers, programs, or any other consumer of the UCS Architecture. The technical governance applies to the following item: - UXS Control Segment (UCS) Architecture: Technical Committee. It is not applicable to third party developers, programs, or any other consumer of the UCS Architecture. Technical Committee. It is not applicable to third party developers, programs, or any other consumer of the UCS A	SAE AS-4UCS Jumanusd Systems (UXS) Contro Segment Architecture	Nov-18		ongoing	
3 datalink and mmunication		AIR6515 Unmanned Systems (UxS) Control Segment (UCS) Architecture: EA Version of UCS ICD Model	This User Guide describes the content of the Enterprise Architect (EA) version of the UCS Architectural Model and how to use this model within the EA modeling tool environment. The purpose of the EA version of the UCS Architectural Interface Control Document (ICD) model is to provide a working model for Enterprise Architect tool users and to serve as the source model for the Rational Software Architect (RSA) and Rhapsody models (AIR6516) and AIR6517). The AIR6515 EA Model has been validated to contain the same content as the AS6518 model for: all UCS ICD interfaces: all UCS ICD to Interfaces all UCS ICD to Interfaces all UCS ICD to Interfaces. The Domain Participant, Information, Service, and Nor Functional Properties Models. Preconditions for using the AIR6515 EA Model include: access to / experience with Enterprise Architect 10 or higher, Corporate Editionexperience with the Unified Modeling Language (UML) \$\overline{\text{W}}\$ -an understanding of the UCS Architectural Model as originally created in the EA Model AS6518—MODEL	SAE AS-4UCS Unmanned Systems (UxS) Control Segment Architecture		information report	published	
3 datalink and mmunication		AIR6516 Unmanned Systems (UxS) Control Segment (UCS) Architecture: RSA Version of UCS ICD Model	This User Guide describes the content of the Rational Software Architect (RSA) version of the UCS Architectural Model and how to use this model within the RSA modeling tool environment. The purpose of the RSA version of the UCS Architectural Interface ICD model is to provide a model for Rational Software Architect (RSA) users, derived from the Enterprise Architect (EA) ICD model (AIR6515). The AIR6515 EA Model, and by derivation, the AIR6516 RSA Model, have been validated to contain the same content as the AS6518 model for: – all UCS ICD interfaces – all UCS ICD messages – all UCS ICD data directly or indirectly reference by ICD messages and interfaces – the Domain Participant, information, Service and Non Functional Properties Models. Preconditions for using the AIR6516 RSA Model includes—access to Rational Software Architect. Version 9.0 or higher. This release was checked with version 9.1.1. – experience with the Unified Modeling Language (UML) ½; an understanding of the UCS Architectural Model as originally created in the EA model AS6518 MODEL.	SAE AS-AUCS Unmanned Systems (UxS) Control Segment Architecture		Information Report	published	

			This User Guide describes the content of the Rhapsody version of the UCS				
C3 datalink a communicati		AIR6517 Unmanned Systems (UxS) Control Segment (UCS) Architecture: Rhapsody Version of UCS ICD Model	Architectural Model and how to use this model within the Rhapsody modeling tool environment. The purpose of the Rhapsody service of the UCS Architectural Model and how to use this model within the Rhapsody was a Architectural Rhapsody users, derived from the Rhapsody users and the Rhapsody was the Rhapsody users and the Rhapsody users and the Rhapsody users are the Rhapsody users and the Rhapsody users are the Rhapsody users and the Rhapsody users are the Rhapsody users and the Rhapsody Architect for System Engineers, version 8.1 ft July segretions with the Rhapsody Architect for System Engineers, version 8.1 ft July segretions with the Unified Modeling Language (UNII) July and understanding of the UCS Architectural Model as originally created in the EA model ASS518-MODEL	SAE AS-4UCS Urmanned Systems (UxS) Control Segment Architecture	information report	published	
C3 datalink communicati			The Use Case Trace (UCTRACE) is SAE publication AIR6519 of the Department of Defense Immanned Control Segment (UCS) Architecture. This document is the SAE publication of the Department of Defense UAS Control Segment (UCS) Architecture: Use Case Trace (UCTRACE) Version 3.4(PR) approved for Distribution A public release 15.5-1859. This information is produced from a script run against the System Use Case Model contained in the UCS Architecture Model ASS618-MODEL eap configuration item. The System Use Case Model includes, at its lowest level elaboration, use cases Level 273 (2/LS) that describe specific scenarios of message exchanges between Actors and internal system Participants via ServiceInterfaces. These message exchanges provide a way to create detailed traces that answer the question: "What UCS service interfaces must my components implement to satisfy functional requirements represented by a given Level 25 UCS use case?" The AIR6519-UCTRACE spreadsheet contains trace information derived directly from the message sequences in the L2/L3 use cases.	20-Dec-16	information report	published	
C3 datalink communicati		AIR6520 Unmanned Systems (UxS) Control Segment (UCS) Architecture: Version Description Document	Governance of the Unmanned Aircraft System (UAS) Control Segment (UCS) Architecture was transferred from the United States Office of the Secretary of Defense (OSD) to SAE International in April 2015. Consequently, a subset of the UCS Architecture Library Release 3.4(PR) has been published under SAE as the Unmanned Systems (UxS) Control Segment (UCS) Architecture, A95512. This Version Description Document (VDD) describes the correspondence and differences between the two architecture libraries.	SAE AS-4UCS Unmanned Systems (UxS) Control Segment Architecture	Information Report	published	
C3 datalink communicati		AIR6521 Unmanned Systems (UxS) Control Segment (UCS) Architecture: Data Distribution Service (DDS)	This platform specific Interface Control Document (ICD) provides an example mapping to the Object Management Group's (OMG) Data Distribution Service (DDS) Intrastructure middleware. The mapping is based on the Unmanned Systems (UKS) Control Segment (UCS) Architecture: Model, AS6518. A series of non-normalive implementation choices have been made that are specific to this ICD. These implementation: The machine readable ICD and result of this mapping and implementations. The machine readable ICD and result of this mapping and implementation choices are provided with AIR6521. Use and understanding of this document assumes a working knowledge of the UCS Architecture, the model structure and its contents.	SAE AS-AUCS Unmanned Systems (UxS) Control Segment Architecture	information report	published	
C3 datalink a		AS6512 Unmanned Systems (UxS) Control Segment (UCS) Architecture: Architecture Description	This document is the Architecture Description (AD) for the SAE Unmanned Systems (UxS) Control Segment (UCS) Architecture: This AD serves as the official designation of the UCS Architecture - SAE AS6512. The UCS Architecture is expressed by a library of SAE publications as referenced herein. The other publications in the UCS Architecture Library are: AS6513, AIR6514, AIR6515, AIR6516, AIR6517, AS6518, AIR6519, AIR6520, AIR6521.	SAE AS-4UCS Unmanned Systems (UxS) Control Segment Architecture	standard	published	
C3 datalink a communicati			This document is the authoritative specification within the SAE Unmanned Systems (UkS) Control Segment (UCS) Architecture for establishing conformance requirements for UCS products. The UCS products addressed by this specification are UCS software configurations that provide one or more UCS services, and UCS systems that employ one or more UCS services. The conformance of UCS products is determined by assessing the conformance of UCS product description to the UCS product description includes test artifacts.	SAE AS-4UCS Unmanned Systems (UxS) Control Segment Architecture	standard	published	
C3 datalink communicati		AS6518 Unmanned Systems (UxS) Control Segment (UCS) Architecture: UCS Architecture Model	This brief User Guide recaps the content of the A85518 UCS Architectural Model described in detail in A85512 UCS Architecture. Architecture Description. The purpose of the UCS Architecture Model is to provide the authoritative source for other models and products within the UCS Architecture as shown in the A85618 UCS Architecture. Architecture as shown in the A85618 UCS Architecture. Architecture are used in clude: -access to / experience with Enterpise Architect 10 or higher, Corporate Edition experience with the Unified Modeling Language (UML) -installation of the [Included UCS, MDC, MDC and add in for Sparx Enterprise Architect per instructions below	SAE AS-4UCS Umanned Systems (UxS) Control Segment Architecture	standard	published	

C3 datalink and communication			AS6522 Unmanned Systems (UxS) Control Segment (UCS) Architecture: Architecture Technical Governance	The UCS technical governance comprises a set of policies, processes, and standard definitions to establish consistency and quality in the development of architecture artifacts and documents. It provides guidance for the use of adopted industry standards and modeling conventions in the use of Unified Modeling Language (UML) and Service Oriented Architecture Modeling Language (SoaML), including where the UCS Architecture deviates from normal UML conventions. This document identifies the defining prolicies, guidelines, and standards of technical governance in the following subjects: undustry standards and specifications adopted by AS-4UCS in the peneration and documentation of the architecture – UCS Architecture – UCS Architecture – UCS appecific policies on the development of the UCS Architecture. The AS-4UCS Technical Committee: Toese are the industry standards and specifications adopted by AS-4UCS in the operation and documentation of the architecture – UCS Architecture. The AS-4UCS Technical Committee of the follow a consistent set of specifications and industry best practices. Standards are referenced within policies. Standards may place constraints on policies that are implemented by processes. Each process is intended to guide the development of architecture artifacts. For example, a standard may dictate that a UML diagram be modeled in a particular methodology using only approved stereotypes from the SoaML UML profile. UCS technical governance applies to the following technical work products that are generated within the AS-4UCS Technical Committee. It is not applicable to the following developers, programs, or any other consumer of the UCS Architecture.	SAE AS-4UCS Urmanned Systems (UKS) Control Segment Architecture		standard	published	
Navigation			WK58931 Evaluating AerialResponse RobotManeuvering: Maintain Position and Orientation	A suite of standard test methods has been developed to measure manusevrability, endurance, communications, durability, logisitics, autonomy, and safety to guide purchasing decisions, support operator training and measure proficiency.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	Publication Delayed -Full Committee Meting Feb 28- Mar 2 2018 for adudication of comments
Navigation			a Point	A suite of standard test methods has been developed to measure manueverability, endurance, communications, durability, logisitics, autonomy, and safety to guide purchasing decisions, support operator training and measure proficiency.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	Publication Delayed -Full Committee Meting Feb 28- Mar 2 2018 for adudication of comments
Navigation			WK58933 Evaluating AerialResponse RobotManeuvering: Avoid Static Obstacles	A suite of standard test methods has been developed to measure manueverability, endurance, communications, durability, logisitics, autonomy, and safety to guide purchasing decisions, support operator training and measure proficiency.	ASTM E54 Homeland Security Applications	Jun-18	standard	ongoing	
Navigation			WK58934 Evaluating AerialResponse RobotManeuvering: Pass Through Openings	A suite of standard test methods has been developed to measure manueverability, endurance, communications, durability, logisitics, autonomy, s and safety to guide purchasing decisions, support operator training and measure proficiency.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	Publication Delayed -Full Committee Meting Feb 28- Mar 2 2018 for adudication of comments
Navigation			Accurately (Vertical)	A suite of standards test methods has been developed to measure manueverability, endurance, communications, durability, logistitics, autonomy, d and safety to guide purchasing decisions, support operator training and measure proficiency.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	Publication Delayed -Full Committee Meting Feb 28- Mar 2 2018 for adudication of comments
C3 datalink and communication			WK58942 Evaluating AerialResponse RobotRadio Communication Range: Line of Sight	A suite of standards test methods has been developed to measure manueverability, endurance, communications, durability, logistitics, autonomy, and safety to guide purchasing decisions, support operator training and measure proficiency.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	Publication Delayed -Full Committee Meting Feb 28- Mar 2 2018 for adudication of comments
C3 datalink and communication			WK58941 Evaluating AerialResponse RobotRadio Communications Range: Non Line of Sight	A suite of standards test methods has been developed to measure manueverability, endurance, communications, durability, logistitics, autonomy, and safety to guide purchasing decisions, support operator training and measure proficiency.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	Publication Delayed -Full Committee Meting Feb 28- Mar 2 2018 for adudication of comments
C3 datalink and communication			STANAG 4660 - Interoperable Command and Control Datalink for Unmanned Systems	Common standard Line-Of-Sight command and control data link for the safe and reliable operation of unmanned systems within a joint, coalition and controlled airspace operating environment.	NATO NNAG/JCGUAS		standard	published	
Navigation			SAE6856 Improving Navigation Solutions Using Raw Measurements from Global Navigation Satellite System (GNSS) Receivers	This recommended practice provides users with the technical requirements and methods for accessing, viewing, and processing raw GNSS receiver measurements for improved unmanned vehicle navigation solutions.	SMCPNT Position, Navigation, and Timing Committee	Mar-19	standard	ongoing	
Navigation			SAE6857 Requirements for a Terrestria Based Position, Navigation, and Timing (PNT) System to Improve Navigation Solutions and Ensure Critical Infrastructure Security	This recommended practice defines the technical requirements for a terrestrial-based PNT system to improve vehicle (e.g. unmanned, aerial, ground, martimel positioning/mayalian solutions and ensure critical infrastructure security, complementing GNSS technologies.	SMCPNT Position, Navigation, and Timing Committee	Mar-19	standard	ongoing	
C3 datalink and communication			MASPS on C3 Spectrum Management for the 5030/5091 MHz band	Minimum Aviation Systems Performance Standard defining requirements for the management of the 5030/5091 MHz band fir use by C2 Link Services	EUROCAE WG-105	Dec-20	standard	ongoing	
C3 datalink and communication			Guidance on Spectrum Access, Use and Management	Guidance material describing considerations for the use of spectrum for UAS purposes	EUROCAE WG-105	Mar-19	guidance	publised	

	Cyber security	EU 2019/945	Part 3(8) and 4(12) UAS in class C2 and C3 shall be equipped with a data link protected against unauthorised access to the command and control functions;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover 'Specific' or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, flammabilit	ASD-STAN DSWG8	Dec-24	preEN / European standard	Published	
	Cyber security							MASPS on RPAS C3 Security	Minimun Aviation Systems Performance Standard defining system level requirements for the application of Security measures to the UAS C3 Link	EUROCAE WG-105	Jun-19	standard	on hold	
	C3 datalink and communication							Guidance on RPAS C3 security	Guidance material for the application of the MASPS listed above	EUROCAE WG-105	Dec-19	guidance	on hold	
	C3 datalink and communication	EASA Decision	OSO#6 C3 link performance is appropriate for the operation	EASA	Oct-19	Specific	published							
	C3 datalink and communication	EASA Decision	OSO#16 Multi crew coordination. (Criterion #3 Communication devices)	EASA	Oct-19	Specific	published							
	C3 datalink and communication							MOPS	Minimum Operational Performance Specification for UAS Communications by Cellular Networks	EUROCAE WG-105 SG-2	Q2-2023	standard	ongoing	
	C3 datalink and communication							EUROCAE Report	UAS C2 MASPS European Stakeholders Report	EUROCAE WG-105 SG-2	Q2-2023	report	ongoing	
	C3 datalink and communication							ASTM	ASTM F1583-95 (2019): Standard Practice for Communications Procedures – Phonetics	ASTM		standard	published	Standard added to RDP as it was recommended by AW- Drones
4									nd Avoid					
М	Detect and avoid							EUROCAE Document ED-271	Minimum Aviation System Performance Standard for DAA [Traffic] in class A-C airspaces under IFR	EUROCAE WG-105	5/11/2022	standard	published	Published May 2022
	Detect and avoid							OSED	Operational Services and Environment Description for DAA for DAA in Class D-G airspaces under VFR/IFR	EUROCAE WG-105	Jan-19	standard	published	
	Detect and avoid							MASPS	Minimum Aviation System Performance Standard (End-to-end Requirements at system level) for DAA against conflicting traffic for RPAS operating under IFR and VFR in all airspace classes	EUROCAE WG-105	Q2-2023	standard	ongoing	target date changed
	Detect and avoid							MOPS	Minimum Operational Performance Standard (Requirements at equipment level) for DAA against conflicting traffic for RPAS operating under IFR and VFR in all airspace classes	EUROCAE WG-105 EUROCAE	Q2-2024	standard	ongoing	planned changed to ongoing
	Detect and avoid							OSED	ED-267 OperationalServices and Environmental Description for DAA in very Low Level Operations	WG-105	Jun-20	standard	published	
	Detect and avoid							MOPS	Minimum Operational Performance Standard (Requirements at equipment level) for DAA at Very Low Level (VLL)	EUROCAE WG-105	Q2-2024	standard	ongoing	target date changed
	Detect and avoid							STANREC 4811 Ed. 1/ AEP 101 Ed. A Ver.1 "UAS sense and avoid"	To detail comprehensive guidance and recommended practice for the development of Sense and Avoid systems, referencing and providing guidance regarding application of existing standards and best practice. Defines minimum performance standards	NATO FINAS	Feb-18	guide	published	
	Detect and avoid							F3442-20 Specification for Detect and Avoid Performance Requirements	Detries minimum performance standards Comprehensive DAA Standard under annex to define test methods AND minimum performance standards for DAA systems and sensors applicable to smaller UAS BLVOS operations for the protection of manned aircraft in lower altitude airspace	ASTM F38 Unmanned Aircraft Systems		standard	published	Publication expected
	Detect and avoid							WK62669 Test Method for DAA	Covering systems and sensors Comprehensive DAA Standard under annex to define test methods AND minimum performance standards for DAA systems and sensors applicable to smaller UAS BLVOS operations for the protection of manned aircraft in lower altitude airspace.	ASTM F38 Unmanned Aircraft Systems	Jun-19	standard	ongoing	Working Group formed under terms of reference. Number changed to WK62669 instead of WK62668
	Detect and avoid							EUROCAE Report	European Industry Position Report on RTCA SC-147 ACAS sXu	EUROCAE WG-105	Dec-22	report	ongoing	
	Detect and avoid							RTCA	RTCA DO-365: MOPS for Detect and Avoid (DAA) Systems - Phase 1	RTCA SC-228	May-2017	standard	published	Standard added to RDP as it was recommended by AW- Drones
	Detect and avoid							RTCA	RTCA DO-366: Minimum Operational Performance Standards (MOPS) for Air-to-Air Radar for Traffic Surveillance	RTCA SC-228	May-2017	standard	published	Standard added to RDP as it was recommended by AW- Drones Standard added to RDP as it
	Detect and avoid							EUROCAE and RTCA	ED-275 Vol. 1/RTCA DO-386: Minimum Operational Performance Standards for Airborne Collision Avoidance System Xu (ACAS Xu)	EUROCAE		standard	published	was recommended by AW- Drones
5								RPAS AU	tomation					
	Development assurance (Software)							ASTM F3269 Standard Practice for Methods to Safely Bound Flight Behavior of Unmanned Aircraft Systems Containing Complex Functions	This standard practice defines design and test best practices that if followed, would provide guidance to an applicant for providing evidence to the civil aviation authority (CAA) that the flight behavior of an unmanned aircraft system (UAS) containing complex function(s) is constrained through a runtime assurance (RTA) architecture to maintain an acceptable level of flight safety.	ASTM F38 Unmanned Aircraft Systems		standard	published	FAA Notice Of Availability (NOA) Pending approval of ASTM WK57659 as foundational document
М	Automatic modes, takeoff, Landing, taxing								Goal is to develop the standard to a level of capability that defines run-lime monitoring (RTA) attributes to a level that the FAA or CAA will agree that monitors developed to this standard are sufficient to allow the UAS to evolve the complex function with its associated avionics equipment and sensors without requiring vehicle recertification as the CONPS evolve after initial certification. a. Provide additional guidance on partitioning, dissimilarity, and the option for multiple individual safety monitor casses and key attributes. b. Provide additional use cases as Appendices or, e. Provide additional information contrasting the Fa269 approach with other architectural approaches (e.g., SAE ARP 4754A, RTCA DO-178C). d. Modify requirements to performance based to allow multiple implementation and implementation architectures e. Make additional updates as required.	ASTM F38.01		standard	published	

	Automatic modes, takeoff, Landing, taxing							ED-252 OSED	Operational Services and Enironment Description for Automatic Take-Off and Landing.	EUROCAE WG-105		standard	published	
	Automatic modes, takeoff, Landing, taxing							MASPS	ED-283 Minimum Aviation System Performance Standard (End-to-end Requirements at system level) for Automatic Take-Off and Landing	EUROCAE WG-105	Jun-20	standard	published	
	Automatic modes, takeoff, Landing, taxing							ED-251 OSED	Operational Services and Enironment Description for Automatic Taxing	EUROCAE WG-105		standard	published	
	Automatic modes, takeoff, Landing, taxing							MASPS	Minimum Aviation System Performance Standard (End-to-end Requirements at system level) for Automatic Taxling	EUROCAE WG-105	Jun-20	standard	published	
	Emergency recovery/terminat ions systems	EU 2019/945	Parts 2(7), 3(7) and 4(5) A UAS Class C1, C2 and C3 shall: in case of a loss of data link, have a reliable and predictable method for the UA to recover the data link or terminate the flight in a way that reduces the effect on third parties in the air or on the ground	EASA	Jun-19	open category and specific	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class 00, C1, C2, C3 and C4 UAS). This document does not cover 'Specific' or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, fluctional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
	Emergency recovery/terminat ions systems							ED-253 OSED	Operational Services and Enironment Description for Automation and Emergency Recovery	EUROCAE WG-105	Dec-18	standard	published	
	Emergency recovery/terminat ions systems							MASPS	ED-281 Minimum Aviation System Performance Standard (End-to-end Requirements at system level) for automation and Emergency Recovery	EUROCAE WG-105	Jun-20	standard	published	
6	iona ayatema	•						Design & Ai	irworthiness					
	Development assurance (Software)							ASTM F3151 Standard Specification for Verification of Avionics Systems1	This specification provides a process by which the intended function and compliance with safety objectives of avoincies systems may be verified by system-level testing. Software and hardware development assurance are not in the scope of this specification and this specification should not be used if a development assurance process is required.	ASTM F39 Aircraft Systems		standard	published	This will be reference in AC for Special Class §21.17(b) To be uses where appropriate in lieu of DO 178. NEW DELIVERABLE
	UA Design and Airworthiness							AS6009A JAUS Mobility Service Set	This document defines a set of standard application layer interfaces called JAUS Mobility Services. JAUS Services provide the means for software entities in an unmanned system or system of unmanned systems to communicate and coordinate their activities. The Mobility Services represent the vehicle platform-independent capabilities commonly found across all domains and types of unmanned systems (referred to as UXVs). At present, over 15 services are defined in this document many of which were updated in this revision to support Unmanned Underwater Vehicles (UUVs).	SAE AS-4JAUS Joint Architecture for Unmanned Systems Committee		standard	published	
	UA Design and Airworthiness							AS5684B JAUS Service Interface Definition Language	The SAE Aerospace Information Report AIR5315 – Generic Open Architecture (GOA) defines "a framework to identify interface classes for applying open systems to the design of a specific hardware/software system." [sae] JAUS Service (Interface) Definition Language defines an XML schema for the interface definition of services at the Class 4L, or Application Layer, and Class 3L, or System Services Layer, of the Generic Open Architecture stack (see Figure 1). The specification of JAUS services shall be defined according to the JAUS Service (Interface) Definition Language document.	SAE AS-4JAUS Joint Architecture for Unmanned Systems Committee		standard	published	
	UA Design and Airworthiness							AS6062 JAUS Mission Spooling Service Set	This document defines a set of standard application layer interfaces called JAUS Mission Spooling Services. JAUS Services provide the means for software entities in an unmanned system or system of unmanned systems to communicate and confinate their activities. The Mission Spooling Services and domains and types of unmanned systems. At present, 1 service is defined into this document (more services are planned for future versions of this document): "Mission Spooler: Stores mission plans, coordinates mission plans, and parcels out elements of the mission plan for execution The Mission Spooler service is described by a JAUS Service Definition (JSD) which specifies the message set and protocol required for compliance. The JSD is fully compliant with the JAUS Service Interface Definition Language [JSIDL].	SAE AS-4JAUS Joint Architecture for Unmanned Systems Committee		standard	published	
	UA Design and Airworthiness							AS6060 JAUS Environment Sensing Service Set	This document defines a set of standard application layer interfaces called JAUS Environment Sensing Services. JAUS Services provide the means to software entities in an unmanned system or system of unmanned systems to communicate and coordinate their activities. The Environment Sensing Services represent typical environment sensing capabilities commonly found across all domains and types of unmanned systems in a platform-independent manner. At present, five services are defined in this document. Range Sensor: Determine the proximity of objects in the platform's environment Vsiusal Sensor: Provides common configuration and setup for different types of imaging systems. Digital Video. A type of Visual Sensor that manages analog video. Still Image: A type of Visual Sensor that manages analog video. Still Image: Each service is described by a JAUS Service Definition (JSD) which specifies the message set and protocol required for compliance. Each JSD is fully compliant with the JAUS Service Interface Definition Language [ASS684].	SAE AS-4JAUS Joint Architecture for Unmanned Systems Committee		standard	published	

нмі	AS6040 JAUS HMI Service Set	across all domains and types of unmanned systems. Five services are defined in this document: • Drawing • Pointing Device • Keyboard • Digital	SAE S-JAJAUS Joint vchitecture for Unmanned stems Committee	standard	published	
UA Design and Airworthiness	AS5710A JAUS Core Service Set	messaging • Access Control: Manages preemptable exclusive control for safety critical operations • Management: Defines component life-cycle	SAE S-4JAUS Joint vchitecture for Unmanned stems Committee	standard	published	
UA Design and Airworthiness	ARP6012A JAUS Compliance and Interoperability Policy	interface of an unmanned system or component in regard to the application of the standard set. While non-SAE AS-4 JAUS documents are referenced in this ABB thou are not within the seems of this document and should be	SAE S-4JAUS Joint Architecture for Unmanned stems Committee	recommended practice	published	
UA Design and Airworthiness	AIR5645A JAUS Transport Considerations	(JAUS). This document provides guidance on the aspects of transport media, unmanned systems and the characteristics of JAUS itself that are	SAE S-4JAUS Joint vrchitecture for Unmanned stems Committee	information report	published	
UA Design and Airworthiness	AS5669A JAUS/SDP Transport Specification	implemented throughout this document, AS5669 can be used for any SDP that meets the required capabilities. A Software Defined Protocol is defined	SAE S-JAJALS Joint vchitecture for Unmanned stems Committee	standard	published	
UA Design and Airworthiness	AS6091 JAUS Unmanned Ground Vehicle Service Set	This document defines a set of standard application layer interfaces called JuliS Unmanned Ground Vehicle Services. JuliS Services provide the means for software entities in an unmanned system or system of unmanned systems to communicate and coordinate their activities. The Unmanned Ground Vehicle Services represent the platform-specific capabilities	SAE S-4JAUS Joint vrohitecture for Unmanned stems Committee	standard	published	
UA Design and Airworthiness	AS6057A JAUS Manipulator Service Set	This document defines a set of standard application layer interfaces called JAUS Manipulator Services. JAUS Services provide the means for software entities in an unmanned system or system of unmanned systems to communicate and coordinate their activities. The Manipulator Services represent platform-independent capabilities commonly found across domains	SAE S-4JAUS Joint vrchitecture for Unmanned stems Committee	standard	published	
UA Design and Airworthiness	ARP6227 JAUS Messaging over the OMG Data Distribution Service (DDS)	CORBA 3.2 specification. This document does NOT address how JAUS transport considerations or JAUS service protocols are implemented on	SAE S-4JAUS Joint Architecture for Unmanned stems Committee	recommended practice	published	
UA Design and Airworthiness	AIR5665B Architecture Framework for Unmanned Systems	unmanned systems domain. The Capabilities View uses terms and concepts from the Conceptual View to describe capabilities of unmanned systems and	SAE S-4JAUS Joint vchitecture for Unmanned stems Committee	information report	published	
UA Design and Airworthiness	AIR5664A JAUS History and Domain Model	Joint Architecture for Unmanned Systems (JAUS); and to capture for posterity the domain analysis that provides the underpinnings for the work by	SAE S-4JAUS Joint Architecture for Unmanned Items Committee	information report	published	

UA Design and Airworthiness		AS6062A JAUS Mission Spooling Service Set	This document defines a set of standard application layer interfaces called JAUS Mission Spooling Services. JAUS Services provide the means for software entities in an ummanied system or system of unmanned systems to communicate and coordinate their activities. The Mission Spooling Services represent the platform-independent capabilities commonly found across all domains and types of ummanied systems. All present, I service is defined this document (more services are planned for future versions of this document). Mission Spooler: Stores mission plans, coordinates mission plans, and parcels out elements of the mission plan for execution The Mission Spooler service is described by a JAUS Service Definition (JSD) which specifies the message set and protocol required for compliance. The JSD is fully compliant with the JAUS Service Interface Definition Language [JSDL].	SAE AS-4JAUS Joint Architecture for Unmanned Systems Committee	,	standard	published	
UA Design and Airworthiness		AS6111 JAUS Unmanned Maritime Vehicle Service Set	This document defines a message-passing interface for services representing the platform-specific capabilities common across unmanned maritime vehicles.	SAE AS-4JAUS Joint Architecture for Unmanned Systems Committee	Jun-19	standard	ongoing	
UA Design and Ainvorthiness		AS6971 Test Protocol for UAS Reciprocating (intermittent) Engines as Primary Thrust Mechanism	engine operation, a series of speed and load combinations and/or sequences	SAE E-39 Unmanned Aircraft Propulsion Committee	May-19	standard	ongoing	
UA Design and Ainvorthiness		AS#### Ground support equipment (preheaters, starters, fuel pumps, fuel couplings, fuel mixing, fuel filters, preflight weighthelainer, bore-sighting of payload, storage containers, alignment hardware, wheel chocks, "remove before flight" items, electronic and software links.		SAE E-39 Unmanned Aircraft Propulsion Committee	Jun-19	standard	planned	
UA Design and Airworthiness		AS#### Propeller hubs		SAE E-39 Unmanned Aircraft Propulsion Committee	Jul-19	standard	planned	
UA Design and Airworthiness		ARP#### Propeller Information Report		SAE E-39 Unmanned Aircraft Propulsion Committee	Aug-19	information report	ongoing	
UA Design and Airworthiness		AIR6962 Ice Protection for Unmanned Aerial Vehicles	A review of icing materials that would be educational to a designer of a UAV ice protection system is provided. Additionally, the differences between unmanned and manned ice protection systems are explored along with a discussion on how these differences can be addressed.	SAE AC-9C Aircraft Icing Technology Committee	Dec-18	information report	ongoing	
UA Design and Ainworthiness		ARP94910 Aerospace - Vehicle Management Systems - Flight Control Design, Installation and Test of, Military Unmanned Aircraft, Specification Guide For	This document establishes recommended practices for the specification of general performance, design, text, development, and quality assurance requirements for the flight control related functions of the Vehicle Management Systems (VMS) of military Jumanned Aircraft (UA), the anthome element of Unmanned Aircraft Systems (UAS), as defined by ASTM F 2395-07. The document is written for military unmanned aircraft intended for use primarily in military operational areas. The document also provides a foundation for considerations applicable to safe flight in all classes of airspace.	SAE A-6 Aerospace Actuation, Control and Fluid Power Systems		recommended practice	published	
UA Design and Airworthiness		ARP5724 Aerospace - Testing of Electromechanical Actuators, General Guidelines For	This document provides an overview of the tests, and issues related to testing, that are unique to Electromechanical Actuators (EMAs). The tests, and issues documented, are not necessarily all-inclusive. This document discusses both the tests applicable to EMAs and the test methodologies to accomplish the test objectives. EMAs may be used in a wide variety of applications such as utility, secondary flight controls and primary flight controls, in a wide variety of markets including manned and unmanned civil and military aircraft, small missile fin and thrust vector control applications up to high powered utility and flight controls. EMAs may also have either a rotary or a linear output, be service controlled or use simple open loop point-to-point or other control topologies. As such this document covers a wide range of potential applications, the application of any given test requirement is determined by the application and the user. This document attempts to provide basic guidance on which tests should be considered for various applications. This document also lists tests that are not unique to EMAs, but are still applicable to EMAs, but hese instances a discussion of such tests is not contained in this document, and as applicable, the reader may reference the appropriate documents as indicated in the text. While many EMAA configurations include digital power drive electronics (PDE), the specific tests required for the electronic hardware, software, or firmware are outside the scope of this document.	A-6 Aerospace Actuation, Control and Fluid Power Systems		recommended practice	published	

	UA Design and Airworthiness		AIR744™ Aerospace Auxiliary Power Sources	This SAE Aerospace Information Report (AIR) is a review of the general characteristics of power sources that may be used to provide secondary, auxiliary, or energency power for use in aircraft, space vehicles, missales, remotely piloted vehicles, air cushion vehicles, surface effect ships, or other whicles in which aerospace technology is used. The information contained herein is intended for use in the selection of the power source most appropriate to the needs of a particular vehicle or system. The information may also be used in the preparation of a power source specification. Considerations for use in making a trade study and an evaluation of the several power sources are included. More detailed information relating to specific power sources is available in other SAE Aerospace Information.	A-6 Aerospace Actuation, Control and Fluid Power Systems		information report	published	
	UA Design and Airworthiness		AS50881F Wiring Aerospace Vehicle	This specification covers all aspects in electrical wire interconnection systems (EWIS) from the selection through installation of wiring and wiring devices and optical cabling and termination devices used in aerospace vehicles. Aerospace vehicles include manned and unmanned airplanes, helicopters, lighter-than-air vehicles, missiles and external pods.	SAE AE-8A Elec Wiring and Fiber Optic Interconnect Sys Install Committee		standard	published	
	UA Design and Airworthiness		AS50881G Wiring Aerospace Vehicle	This specification covers all aspects in electrical wire interconnection systems (EWIS) from the selection through installation of wiring and wiring devices and optical cabiling and termination devices used in aerospace whicles. Aerospace vehicles include manned and unmanned airplanes, helicopters, lighter-than-air vehicles, missiles and external pods.	SAE AE-8A Elec Wiring and Fiber Optic Interconnect Sys Install Committee	Dec-18	standard	ongoing	
	UA Design and Airworthiness		AS#### Artificial simulant standards for drone or FOD impact/ingestion	planned	SAE G-28 Simulants for Impact and Ingestion Testing	Dec-19	standard	planned	
	Emergency recovery/terminat ions systems		F3322-18 Standard Specification for Small Ummanned Aircraft System (sUAS) Parachutes	This specification covers the design and manufacture requirements for deployable parachutes of small unmanned aircraft (sUA). This specification defines the design, fabrication, and test requirements of installable, deployable parachute recovery systems (PRS) that are designed to be integrated into a sUA to lessen the impact energy of the system should the sUA fail to sustain normal stable safe flight. Compliance with this specification is intended to support an applicant in obtaining permission from a civil aviation authority (CAA) to fly a sUA over people.	ASTM F38 Unmanned Aircraft Systems	Sept-18	specification	Published	
	UA Design and Airworthiness		F2490-05(2013) Standard Guide for Aircraft Electrical Load and Power Source Capacity Analysis	This guide covers how to prepare an electrical load analysis (ELA) to meet Federal Aviation Administration (FAA) requirements.	ASTM F39 Aircraft Systems		standard	published	Light Sport Aircraft guidance will be revised to apply to UAS.
	maintenance		F2799-14 Standard Practice for Maintenance of Aircraft Electrical Wiring Systems	Damaged wiring or equipment in an aircraft, regardless of how minor it may appear to be, cannot be tolerated. It is, therefore, important that maintenance be accomplished using the best techniques and practices to minimize the possibility of failure.	ASTM F39 Aircraft Systems		standard	published	
м	UA Design and Airworthiness		F3563-22 Specification for Design and Construction of Large Fixed Wing Unmanned Aircraft Systems	To develop an ASTM design and construction standard for larger mass fixed-wing Unmanned Aerial Systems (UAS). Design and Construct Standards are currently in existence for Part 2S General Manned Aircraft as well as for Fixed Wing and VTOL Small UAS (sUAS). There currently exists a gap for Part 2S General Aircraft of the Large Fixed Wing Unmanned Variety. This ASTM standard will serve to fill that gap by including design and construct requirements, best practices, and proposed methods of compliance specific to Large UAS (up to 19,000 bs).	ASTM F38,01	Jun-19	standard	published	Fill industry identified gaps required for the design and construction of UAS under Part 21 or 23
	UA Design and Airworthiness		ASTM F2910-14 Standard Specification for Design and Construction of a Small Unmanned Aircraft System (sUAS)	This specification establishes the design, construction, and test requirements for a small unmanned aircraft system (sUAS), it is intended for a SUAS that are permitted to operate over a defined area and in airspace authorized by a nation's governing aviation authority (GAA). Unless otherwise specified by a nation's GAA, this specification applies only to UA that have a maximum takeoff gross weight of 55 lb/25 kg or less.	ASTM F38 Unmanned Aircraft Systems		standard	published	This will be reference in AC for Special Class §21.17(b)
	UA Design and Airworthiness		F3298-19 Standard Specification for Design, Construction, and Verification of Lightweight Unmanned Aircraft Systems (UAS)	This specification covers the airworthiness requirements for the design of fixed-wing unmanned aircraft systems. This specification defines the baseline design, construction, and verification requirements for an unmanned aircraft system (UAS)	ASTM F38 Unmanned Aircraft Systems		standard	published	Title change
	UA Design and Airworthiness		ASTM WK63678/ WK64619 Revision of F3298 - 18 Standard Specification for Design, Construction, and Verification of Fixed- Wing Unmanned Aircraft Systems (UAS)	advisory circular for 21-17(b). This required a rapid-action reorganization of the standard, inclusion of VTOL-specific items and a title change.	ASTM F38 Unmanned Aircraft Systems	19-Nov	standard	In progress	Ballot pending Sub- Committee approval
	Manufacturer organisation		ASTM F2911-14e1 Standard Practice for Production Acceptance of Small Unmanned Aircraft System (sUAS)	This standard defines the production acceptance requirements for a small unmanned aircraft system (sIAS). This standard is applicable to sIAS that comply with design, construction, and test requirements identified in Specification F2910. No sUAS may enter production until such compliance is demonstrated.	ASTM F38 Unmanned Aircraft Systems		standard	published	
	Manufacturer organisation		ASTM F3003-14 Standard Specification for Quality Assurance of a Small Unmanned Aircraft System (sUAS)	manufacture, and production of a small unimaritied aircraft system (SOAS).	ASTM F38 Unmanned Aircraft Systems		standard	published	
	Batteries/fuel cell power generating system		WKWK60937 Standard Specification for design of Fuel Cells for Use in Unmanned Aircraft Systems (UAS)	This standard will suffice acception to the constitution of first and	ASTM F38 Unmanned Aircraft Systems	TBD	standard	ongoing	

	Development assurance (Software)							ASTM F3201-16 Standard Practice for Ensuring Dependability of Software Used in Unmanned Aircraft Systems (UAS)	This standard practice intends to ensure the dependability of UAS software. Dependability includes both the safety and security aspects of the software. This practice will focus on the following areas: (a) Organizational controls (for example, management, training) in place during software development. (b) Use of the software in the system, including its architecture and contribution to overall system safety and security. (c) Metrics and design analysis related to assessing the code. (d) Techniques and tools related to code review. (e) Quality assurance. (f) Testing of the software.	ASTM F38 Unmanned Aircraft Systems		standard	published	
	UA Design and Airworthiness							ASTM WK16285 New Specification for Design and Performance of an Unmanned Aircraft System-Class 1320 (550# Gross Weight to 1320# Gross Weight)	The specification covers airworthiness requirements for an acceptable powered fixed wing aircraft UAS.	ASTM F38 Unmanned Aircraft Systems	TBD	standard	ongoing	This work item will be continued using guidelines from ASTM F37 Light Spo Aircraft Committee
	maintenance							ASTM F2909-14 Standard Practice for Maintenance and Continued Airworthiness of Small Unmanned Aircraft Systems (sUAS)	This standard is written for all sUAS that are permitted to operate over a defined area and in arrspace authorized by a nation's governing aviation authority (GAA). It is assumed that a visual observer(s) will provide for the sense and avoid requirement to avoid collisions with other aircraft and that the maximum range and altitude at which the sUAS can be flown will be specified by the nation's GAA. Unless otherwise specified by a nation's GAA this standard applies only to UA that have a maximum take off gross weight of 25 kg (55 lb) or less. The sUAS shall be maintained for continued airworthiness to meet sUAS limitations and performance capabilities required by the nation's GAA.	ASTM F38 Unmanned Aircraft Systems		standard	published	Updated revision underway under WK WK63991
	UA Design and Airworthiness							prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover "Specific" or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-21	preEN / European standard	ongoing	
								Guidelines	ED-280 Guidelines for UAS safety analysis for the Specific category (low and medium levels of robustness)	EUROCAE WG-105	Jun 20	Guidance	published	
	Ground control station							MASPS	ED-272 Minimum Aviation System Performance Standard (End-to-end Requirements at system level) for the Remote Pilot Station interface to Air Traffic Control (ATC).	EUROCAE WG-105	Jun-20	standard	published	
М								EUROCAE Document ED-301	Guidelines for the Use of Multi-GNSS Solutions for UAS Specific Category - Low Risk Operations SAIL I and II	EUROCAE WG-105 SG-6	01/09/2022	standard	piblished	
Α								EUROCAE document	Guidelines for the Use of Multi-GNSS Solutions for UAS - Medium Risk	EUROCAE WG-105 SG-6	Q2-2024	standard	ongoing	
								EUROCAE Document	Guidelines on the automatic protection of the flight envelope from human errors for UAS	EUROCAE WG-105 SG-6	Q1-2024	standard	ongoing	
	Emergency recovery/terminat ions systems	EU 2019/945	Part 16(6) and 16(7) UAS in class C5 and C6 shall provide the remote pilot with means to continuously monitor the quality of the command and control link and receive an alert when it is likely that the link is going to be lost or degraded to the extent of compromising the safe conduct of the operation, and another later when the link is lost	EASA	Jun-20	Specific	Opinon published							
	UA Design and Airworthiness	EU 2019/945	Part 1(3) UAS in Class C0 shall have a maximum attainable height above the take-off point limited to 120 m;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover 'Specific' or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
	UA Design and Airworthiness	EU 2019/945	Parts 2(3), 3(2) and 4(2) UAS in Class C1, 12 and C3 shall have a maximum attainable height above the take-off point limited to 120 m or be equipped with a system that limits the height above the surface or above take-off point 120 m or to a value selectable by the remote plot. If the value is selectable, clear information about the height of the UA above the surface or take-off point during flight shall be provided to the remote pilot.	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover 'Specific' or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but in not limited to, physical and mechanical properties, flammability, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
	UA Design and Airworthiness	EU 2019/945	Parts 1(7) and 2(17) UAS in Class C0 and C1 shall, if equipped with a follow-me mode and when this function is on, be in a range not exceeding 50 m from the remote pilot, and make it possible for the remote pilot to regain control of the UA;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the open 'category (class C0, C1, C2, C3 and C4 UAS). This document does not cover 'Specific' or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	

Manufacturer organisation							ISO 21384-2 - Requirements for ensuring the safety and quality of the design and manufacture of UAS	Requirements for ensuring the quality and safety of the design and manufacture UAS. It includes information regarding the UA, any associated remote control station(s), the C2 links, any other required data links and any other system elements as may be required.	ISO TC20/SC16/WG2	Nov-20	standard	ongoing	
UA Design and Airworthiness							STANAG 4671 "UAV System Airworthiness Requirements (USAR)". (Fix wing UAV, MTOW>1 50Kg).	Set of technical airworthiness requirements intended primarily for the airworthiness certification of fixed-wing military UAS with a maximum take-off weight between 150 and 20,000 kg that intend to regularly operate in non-segregated airspace	NATO FINAS			published	
UA Design and Airworthiness							STANAG 4702 "Rotary Wing Unmanned Aerial Systems Airworthiness Requirements" (Rotorcraft UAV, 150Kg <mtow< 3125kg<="" td=""><td>set of technical airworthiness requirements intended for the airworthiness certification of rotary-wing military UAV Systems with a maximum take-off weight between 150 and 3175 kg that intend to regularly operate in non-</td><td>NATO FINAS</td><td></td><td></td><td>published</td><td></td></mtow<>	set of technical airworthiness requirements intended for the airworthiness certification of rotary-wing military UAV Systems with a maximum take-off weight between 150 and 3175 kg that intend to regularly operate in non-	NATO FINAS			published	
UA Design and Airworthiness							STANAG 4703 "Light Unmanned Aircraft Systems Airworthiness Requirements". (Fix wing UAV, 150Kg <mtow).< td=""><td>Minimum set of technical airworthiness requirements intended for the airworthiness certification of fixed-wing Light UAS with a maximum take-off weight not greater than 150 kg and an impact energy of greater than 66 J (49 ft-b) that intend to regularly operate in non-segregated airspace</td><td>NATO FINAS</td><td></td><td></td><td>published</td><td></td></mtow).<>	Minimum set of technical airworthiness requirements intended for the airworthiness certification of fixed-wing Light UAS with a maximum take-off weight not greater than 150 kg and an impact energy of greater than 66 J (49 ft-b) that intend to regularly operate in non-segregated airspace	NATO FINAS			published	
UA Design and Airworthiness							STANAG 4746 "Unmanned Aerial Vehicle System Airworthiness Requirements for Light Vertical Take Off and Landing Aircraft"	Set of technical airworthiness requirements intended for the airworthiness certification	NATO FINAS	2018		ongoing	
UA Design and Airworthiness	EU 2019/945	Parts 1(5), 3(6) and 4(6) UAS in Class CO, C1 and C2 shall be designed and constructed in such a way as to minimise injury to people during operation, sharp edges shall be avoiled, unless technically unavoidable under good design and manufacturing practice. If equipped with propellers, it shall be designed in such a way as to limit any injury that may be inflicted by the propeller blades,	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class Co, 1', 2c, C3 and C4 UAS). This document does not cover "Specific" or "Certified" category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, effectived properties, functional safety, software, readability of the instructions and manual dic. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
UA Design and Airworthiness	EU 2019/945	Parts 2(15), 3(17) and 4(13) A UAS Class C1, C2 and C 3 shall provide the remote pilot with clear warning when the battery of the UA or its control station reaches a low level so that the remote pilot has sufficient time to safely land the UA:	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover "Specific" or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
UA Design and Airworthiness	EU 2019/945	Parts 2(5) and 3(4) UAS in class C1 and C2 shall have the requisite mechanical strength, including any necessary safety factor, and, where appropriate, stability to withstand any stress to which it is subjected to during use without any breakage or deformation that might interfere with its safe flight;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Urmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class CD, C1, C2, C3 and C4 UAS). This document does not cover 'Specific' or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, flammability, electrical properties, floridant safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
UA Design and Airworthiness	EU 2019/945	Parts 2(16), 3(18) and 4(14) UAS in Class C1, C2 and C3 shall be equipped with lights for the purpose of: (a) the controllability of the UA, (b) the conspicuity of the UA at night, the design of the lights shall allow a person on the ground, to distinguish the UA from a manned aircraft;	EASA	Jun-19	open	Regulation applicable	prEN4709-4 Aerospace series - Unmanned Aircraft Systems (UAS) - Security requirements	This European standard will provide means of compliance to cover lighting related requirements for part 2 to 4 of the delegated act. The purpose is to be able to verify that an UA is equipped with lights which: "ensure controllability of the UA ensure constrollability of the UA ensure conspiculty of the aircraft at night, the design of the light shall allow a person on the ground to distinguish a UA from a manned aircraft. The standards will address: "Definition of types, technical requirements and technical parameters of UA lights (e.g. position of lights for different UA categories, intensity for different operation modes) "Definition of purpose, test procedures, requirements and compliance rules to evaluate UA lights."	ASD-STAN D5WG8	Sep-21	preEN / European standard	published	
UA Design and Airworthiness							ARP6336 Lighting Applications for Unmanned Aircraft Systems (UAS)	This SAE Aerospace Recommended Practice (ARP) provides technical recommendations for the application, design and development of lighting for Unnanned Aircraft (UA). The recommendations set forth in this document are to aid in the design of UA lighting for the type or size of aircraft and the operation in the National Aerospace System for which the aircraft is intended.	SAE A-20 Aircraft Lighting Committee	Dec-18	Recommended Practice	ongoing	ongoing

UA Design and Airworthiness	EU 2019/945	Part 2(1) UAS in class C1 shall be made of materials and have performance and physical characteristics such as to ensure that in the event of an impact at terminal velocity with a human head, the energy transmitted to the human head is less than 80 J. or, as an alternative, shall have an MTOM of less than 900 g, including payload;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover 'Specific' or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
UA Design and Airworthiness	EU 2019/945	Parts 1(6) and 2(10) UAS in class C0 and C1 shall be powered by electricity and have a nominal voltage not exceeding 24 V direct current (DC) or the equivalent alternating current (AC) voltage; its accessible parts shall not exceed 24 V DC or the equivalent AC voltage; internal voltages shall not exceed 24 V DC or the equivalent AC voltage unless it is ensured that the voltage and current combination generated does not lead to any risk or harmful electric shock even when the UAS is damaged;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover 'Specific or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
UA Design and Airworthiness							WK58939 Evaluating AerialResponse RobotEnergy/Power: Endurance Range and Duration	A suite of standards test methods has been developed to measure manueverability, endurance,communications, durability, logisitics, autonomy, and safety to guide purchasing decisions,support operator training and measure proficiency.	ASTM E54 Homeland Security Applications	TBD	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018
UA Design and Airworthiness	EU 2019/945	Parts 3(12) and 4(7) UAS in class C2 and C3 shall be powered by electricity and have a nominal voltage not exceeding 48 V DC or the equivalent AC voltage; its accessible parts shall not exceed 48 V DC or the equivalent AC voltage; internal voltages shall not exceed 48 V DC or the equivalent AC voltage; internal voltages shall not exceed 48 V DC or the equivalent AC voltage; internal voltages shall not exceed 48 V DC or the equivalent AC voltage unless it is ensured that the voltage and current combination generated does not lead to any risk or harmful electric shock even when the UAS is damaged;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover "Specific" or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
UA Design and Airworthiness							WK58940 Evaluating AerialResponse RobotEnergy/Power: Endurance Dwell Time	A suite of standards test methods has been developed to measure manueverability, endurance, communications, durability, logisitics, autonomy, and safety to guide purchasing decisions, support operator training and measure proficiency.	ASTM E54 Homeland Security Applications	TBD	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018 ongoing. Delayed till Apr -18
UA Design and Airworthiness							WK58943 Evaluating AerialResponse RobotSafety: Lights and Sounds	A suite of standards test methods has been developed to measure manueverability, endurance, communications, durability, logisitics, autonomy, and safety to guide purchasing decisions, support operator training and measure proficiency.	ASTM E54 Homeland Security Applications	TBD	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018 ongoing. Delayed till Apr -18
UA Design and Airworthiness							F2639-15 Standard Practice for Design, Alteration, and Certification of Aircraft Electrical Wiring Systems	This practice covers design configuration procedures for aircraft electrical wiring systems.	ASTM F39 Aircraft Systems		standard	published	
UA Design and Airworthiness								This practice covers basic inspection procedures for electrical wiring interconnect systems for aircraft electrical wiring systems.	ASTM F39 Aircraft Systems		standard	published	
Batteries/fuel cell power generating system							ASTM F3005-14a Standard Specification for Batteries for Use in Small Unmanned Aircraft Systems (sUAS)	This standard defines the requirements for batteries used in small Unmanned Aircraft Systems (sUAS Small Unmanned Aircraft System	ASTM F38 Unmanned Aircraft Systems		standard	published	Currently being reviewed for updates FAA Notice Of Availability (NOA) Pending approval of ASTM WK57659 as foundational document
UA Design and Airworthiness							F2490-05(2013) Standard Guide for Aircraft Electrical Load and Power Source Capacity Analysis	This guide covers how to prepare an electrical load analysis (ELA) to meet Federal Aviation Administration (FAA) requirements.	ASTM F39 Aircraft Systems		standard	published	
UA Design and Airworthiness	EU 2019/945	Part 5(3) UAS in class C4 shall not be capable of automatic control modes except for flight stabilisation assistance with no direct effect on the trajectory and lost link assistance provided that a pre-determined fixed position of the flight controls in case of lost link is available;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the open category class C0, C1, C2, C3 and C4 UAS). This document does not cover "Specific" or "Certified" category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, florid safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
 UA Design and Airworthiness	Opinion 05- 2019	Part 17(6) UAS in class C4 shall provide means to programme the UA trajectory;	EASA	Jun-20	Specific	Opinion published							

	esign and rthiness	EU 2019/945	Part 3(9) UAS in class C2 shall unless it is a fixed-wing UA. be equipped with a low-speed mode selectable by the remote pilot and limiting the maximum cruising speed to no more than 3 m/s.	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class CO, C1, C2, C3 and C4 UAS). This document does not cover 'Specific' or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical proprieties, fluminosity, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
	esign and rthiness	Opinion 05- 2019	Part 16(4) UAS in class C5 shall be equipped with a low-speed mode selectable by the remote pilot and limiting the ground speed to not more than 5 m/s	EASA	Jun-20	Specific	Opinion published	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover 'Specific' or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
	esign and rthiness	Opinion 05- 2019	Part 16(5) and 17(5) UAS in class CS and CS shall be provide means for the remote plot to terminate the flight of the UA, which shall: (a) be reliable, predictable and independent from the automatic flight control and guidance system; this applies also to the activation of this means; (b) force the descent of the UA and prevent its powered horizontal displacement; and (c) include means to reduce the effect of the UA impact dynamics	EASA	Jun-20	Specific	Opinon published							
	esign and rthiness	EU 2019/945	Parts 3(5) and 4(4) UAS in class C2 and C3 shall in the case of a tethered UA, have a tensile length of the tether that is less than 50 m and a mechanical strength that is no less than: (a) for heavier-than-air aircraft, 10 times the weight of the aerodyne at maximum mass; (b) for lighter-han-air aircraft, 4 times the force exerted by the combination of the maximum static thrust and the aerodynamic force of the maximum allowed wind speed in flight;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover 'Specific' or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical proprites, flammability, electrical protries, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
	esign and rthiness	EU 2019/945	Parts 2(14), 3(16) and 4(11) UAS in class C1, C2 and C3 shall, if the UA has a function that limits its access to certain airspace areas or volumes, this function shall operate in such a manner that it literacts smoothly with the flight control system of the UA without adversely affecting flight safety; in addition, clear information shall be provided to the remote pilot when this function prevents the UA from entering these airspace areas or volumes;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover 'Sepecific' or 'Gereffer' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, functional safety, software, readobility of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
	esign and rthiness	EU 2019/945	Parts 1(2) and 2(2) UAS in class C0 and C1 shall have a maximum speed in level flight of 19 m/s;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover 'Sepecific' or 'Certifier' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
UA De Airwor	esign and	Opinion 05- 2019	Part 17(1) UAS in class C6 shall have a maximum ground speed in level flight	EASA	Jun-20	Specific	Opinon published							
UA De	esign and rthiness	EASA Decision	of not more than 50 m/s; OSO#4 UAS developed to authority recognized design standards (e.g. industry standards)	EASA	Oct-19	Specific	published							
UA De	esign and	EASA Decision	OSO#5 UAS is designed considering system safety and reliability	EASA	Oct-19	Specific	published							
UA De	rthiness esign and rthiness	EASA Decision	OSO#10 Safe recovery from technical issue /	EASA	Oct-19	Specific	published							
UA De	esign and rthiness	EASA Decision	OSO#12 The UAS is designed to manage the deterioration of	EASA	Oct-19	Specific	published							
UA De	esign and	EASA Decision	external systems supporting UAS operation 0S0#18 Automatic protection of the flight envelope from human	EASA	Oct-19	Specific	published							
UA De	rthiness esign and	EASA Decision	errors 0S0#19 Safe recovery from Human Error (<u>Criterion #3 UAS</u>	EASA	Oct-19	Specific	published							
Airwor	rthiness	EASA Decision	design) 0S0 #20 - A Human Factors evaluation has been performed and	EASA	Oct-19	Specific	published							
			the HMI found appropriate for the mission Part 16(3) and 17(3)				-							
НМІ		EU 2019/945	UAS Class C5 and C6 during flight shall provide the remote pilot with clear and concise information on the height of the UA above the surface or take-off point;	EASA	Jun-20	Specific	Opinon published							

нмі	EU 2019/945	Part 1(4) and 2(4) UAS in class C0 and C1 shall be safely controllable with regards to stability, manoeuvrability and data link performance, by a remote pilot following the manufacturer's instructions, as necessary unde	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover "Specific" or "Certified" category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
нмі	EU 2019/945	Part 5(2) UAS in class C4 shall be safely controllable and manoeuvrable by a remote pilot following the manufacturer's instructions, as necessary under all anticipated operating conditions including following the failure of one or, if appropriate, more systems;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover "Specific" or "Certified" category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but in not limited to, physical and mechanical properties, flammability, electrical properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
нмі	EU 2019/945	Part 3(3) and 4(3) UAS in class C2 and C3 shall be safely controllable with regards to stability, manoeuvrability and data link performance, by a remote pilot with adequate competency as defined in Implementing Regulation (EU) [20190517-120] and following the manufacturer's instructions, as necessary under all anticipated operating conditions including following the failure of one or, if appropriate, more systems	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class CO, C1, C2, C3 and C4 UAS). This document does not cover 'Specific' or 'Certified' category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, electrical properties, flammabilit	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
UA Design and Airworthiness	EASA Decision	OSO #24 - UAS designed and qualified for adverse environmental conditions (e.g. adequate sensors, DO-160 qualification)	EASA	Oct-19	Specific	published							
UA Design and Airworthiness	EASA Decision	OSO#24 UAS designed and qualified for adverse environmental conditions (e.g. adequate sensors, DO-160 qualification)	EASA	Oct-19	Specific	published							
UA Design and Airworthiness	EASA Decision	M#2 Effects of ground impact are reduced. A category. Measures reducing the effect of the UAS impact dynamics (e.g. emergency parachute).	EASA	Oct-19	Specific	published							
Airworthiness	Opinion 05- 2019	Part 16 A class CS UAS may consist in a class C3 UAS fitted with an accessories kit that ensures the conversion of the UAS into a class CS UAS. In this case, the class C5 label is affixed on the accessories kit. An accessories kit may only ensure conversion of a class C3 UAS that complies with (1) and provides the necessary interfaces to the accessories. The accessories kit shall not include changes to the software of the class C3 UAS. The accessories kit shall be designed, and each accessory shall be identified, to ensure a complete and correct installation by a UAS operator on a class C3 UAS following the instructions provided by the manufacturer of the accessories kit thay be placed on the market independently from the class C3 UAS of which they ensure the conversion. In this case, the manufacturer of the accessories kit shall place on the market a single conversion kit that shall. [1] not alter the compliance of the class C3 UAS with the requirements of Part 4; [2] ensure compliance of the UAS fitted with the accessories kit with all additional requirements defined in this Part with the exception of paragraph 3	EASA	Jun-20	Specific	Opinon published							
UA Design and Airworthiness	EASA Decision	M#3 Technical containment in place and effective (e.g. tether)	EASA	Oct-19	Specific	published							
							ASTM WK67357 New Specification for Light Unmanned Aircraft System Manufacturers Quality Assurance System	This specification establishes the minimum requirements for a quality assurance system for manufacturers of Light Unmanned Aircraft Systems or Light Unmanned Aircraft System kits, or both.	ASTM F38 Unmanned Aircraft Systems	Mar-19	specification	ongoing	
							ASTM WK 63407 Standard Specification for Required Product Information to be Provided with a Small Unmanned Aircraft System	This specification covers the minimum requirements for information that shall be provided by the sUAS OEM or seller of a new small unmanned aircraft stransfer spreaders, or accessories (that is, radio, automated flight control system, remote pilot station, GPS, and so (crit) as a part of the initial sellor of transfer to the first end user. This specification does not apply to the sale or transfer of used small unmanned aircraft, engines, propelers, or accessories. This specification applies to small unmanned aircraft systems seeking out alwation authority approval in the form of airvorthiness certificates or other like documentation.	ASTM F38 Unmanned Aircraft Systems	Oct-19	standard	ongoing	currently under ballot
							F3478-20 Standard Practice for Development of a Durability and Reliability Flight Demonstration Program for Low-Risk Unmanned Aircraft Systems (UAS) under FAA Oversight	Demonstration plans developed in accordance with this practice will include all necessary content and key considerations to support an effective flight demonstration program aimed at approval or certification of UAS by the FAA through D&R demonstration.	ASTM F38 Unmanned Aircraft Systems		standard	published	

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				ED-279 Generic Functional Hazard Assessment (FHA) for UAS and RPAS	This document aims at generating a UAS/RPAS FHA, to cover the widest possible number of configurations with the sim of providing UAS system diseologers is framework to support designers when performing the FHA process. In order to support this, the core functions of a UAS have been identified (slightly tailored from the functions list in draft ARPA761-A for manned platforms) and assessed independently of each other. The production of a Basic FHA is challenging due to the large variance in UAS configurations, mensing that essential functions may not in all cases to be considered independently. Because of this, additional rules have been developed to support the generation of an FHA specific to the implementation being consideration.	EUROCAE WG-105		standard	published	
				ED-280A Generic Functional Hazard Assessment (FHA) for UAS and RPAS	Guidelines for UAS safety analysis for the Specific category (low and medium levels of robustness)	EUROCAE WG-105	Q1-2024	standard	ongoing	
				ISO/WD 24352	Tech Requirements for small UAS Electric Energy System	ISO TC20 SC16		standard	ongoing	
				ASD-STAN C5-C6 / Safety	Flight Termination System - technical specification and the verification methods for the remote pilot to terminate the flight of the UA in case of emergency during the flight address a list of functions and describe the levels of reliability related to safety specifications and verification method for the Flight Termination System components will mainly cover the following features: - GNSS3 receiver integrity level and resistance to jamming interface to trigger the emergency devices such as parachute for VTOL4 or emergency landing for CTOL5 - interface to torget the emergency devices such as parachute for VTOL4 or emergency landing for CTOL5 - interface to torgot the system (e.g., propulsion shutdown, circuit breaker, etc.) - energy supply for the Flight Termination System - Radio Frequency communication capability from C26 link - UA impact dynamics - Flight Termination System warning and alert messages for the remote pilot	ASD-STAN D5WG8-SG7	May-2022	standard	ongoing	
	Geo-caging			ASD-STAN C5-C6 / Safety	Geo-caging - verification method for the Geo-caging function intended to avoid any potential breach of airspace limitations defined by the users and set into the airborne system before the flight - verify that the geo-caging function will use the same data model defined for the airspace and used for the geo-awareness function as defined by EN 4109-003. - verification method for the drone trajectory modification function to keep the drone inside the defined operational volume, which is the focus of the geo- caging function. describe the means to prevent the UA2 from breaching the horizontal and vertical limits of the operational volume and the size of the contingency volume needed to accommodate position assessment error, reaction time and correction maneuver span.	ASD-STAN D5WG8-SG6	May-2022	standard	ongoing	
				ASD-STAN C5-C6 / Design & Accessories Kit	General product requirements for different UAS classes operating under declaration and accessories kits - technical specification and the verification methods for C5 and C6 UAS and the accessories kits to transform class C3 UA into class C5 UA. specifications and verification methods for class C5 UAS product requirements: information during flight related to the height of the UA above the surface or take-off point selectable limitation of the ground speed C2 link monitoring warning and alert messages related to the degradation or loss of link - specifications and verification methods for the class C6 UAS product requirements: inimitation of the ground speed C2 link monitoring warning and alert messages related to the degradation or loss of link information during flight (including the geographical position of the UA, the speed, and the height of the UA above the surface or take-off point) UA trajectory program - specifications and sert methods for the accessories kits to transform a class C3 UA into class C5 UA: design of the accessories kits components; interfaces between the drone and the accessories kits to set-up the accessories kits	ASD-STAN D5WG8-SG1	June-2022	standard	ongoing	
				EUROCAE Guidance Document	Guidance document to support the development of Means of Compliance (MoC) for EASA Special Condition Light-UAS – Medium Risk	EUROCAE WG- 105 SG-4	Q1-2023	standard	ongoing	
				EUROCAE Document	Minimum Operational Performance Standard for Command Unit Core Layer of UAS to be operated in the EASA certified category of operations	EUROCAE WG- 105 SG-4	Q1-2023	standard	ongoing	
				EUROCAE Document	Guidelines for SAIL II application of SORA	EUROCAE WG- 105 SG-6	Q4-2023	standard	ongoing	
A				WK82742 Standard Practice for To support UAS manufacturers in obtaining Production Approval in concert with Type Certification for UAS WK71061 Lightweight	ASTM has released standards (i.e., E2911-14E1, F2930-16E1, F2972-15, F3033-22, F3198-18, F2839-11, F3003-14, F2035-71) in support F3035-22, F3198-18, F2839-11, F3003-14, F2035-71) in support of manufacturing of light sport aircraft and small UAS (sUAS). These standards include best practices for promoting production compliance, however recently emerging unique aspects of UAS type certification (e.g., Durability and Reliability means of compliance, Associated Elements, Certified Category) require UAS-specific production approval for only guidance to the UAS community. Part of this task/activity will be to evaluate the other ASTM standards for relevance to production approval for UAS and leverage existing standards insofar as practicable. The purpose is to address the basic fundamental subject knowledge, task	STM F38.01	Jui-23		ongoing	New Working Group Established
A				UAS Maintenance Technician Qualification	performance, and task knowledge activities and functions for UAS	ASTM F46	Feb-23		ongoing	
7				Oper	ations					

Operations		AS6062 - Mission Spooling Service Set	This document defines a set of standard application layer interfaces called JAUS Mission Spooling Services. JAUS Services provide the means for software entities in an unmanned system or system of unmanned systems to communicate and coordinate their activities. The Mission Spooling Services represent the platform-independent capabilities commonly found across all domains and types of unmanned systems. At present, 1 service is defined in this document, 1 mission Spooler stores mission plans, coordinates mission plans, and parcels out elements of the mission plan for execution The Mission Spooler softs of the mission plan for execution The Mission Spooler service is described by a JAUS Service Definition (JSD) which specifies the message set and protocol required for compliance. The JSD is fully compliant with the JAUS Service Interface Definition Language [USIDL].	SAE AS-4JAUS Joint Architecture for Unmanned Systems Committee		standard	published	
Qualified entil	ites	ASTM F3364-19 Standard Practice for Independent Audit Program for Unmanned Aircraft Operators	Minimum requirements, responsibilities, qualifications for entities conducting internal audits against ASTM standards on Unmanned Aircraft Systems	ASTM F38 Unmanned Aircraft Systems		standard	published	
Qualified entil	ites	F3365-19 Standard Practice for Compliance Audits to ASTM Standards on Unmanned Aircraft Systems	—How to conduct a third party audit program for those who execute audits to meet the consensus set of minimum requirements and qualifications.	ASTM F38 Unmanned Aircraft Systems		standard	published	
Qualified entii	ites	ASTM WK62744 General Operations Manual for Professional Operator of Light Unmanned Aircraft Systems (UAS)	Best practices to support professional entities receiving operator certification by a CAA, and provide practice for self- or third-party audit of operators of UAS.	ASTM F38 Unmanned Aircraft Systems	TBD	Best practice	ongoing	Draft
Manuals		ASTM F2908-16 Standard Specification for Aircraft Flight Manual (AFM) for a Small Unmanned Aircraft System (sUAS)	This specification provides the minimum requirements for an Aircraft Flight Manual (AFM) for an unmanned aircraft system (UAS) designed, manufactured, and operated in the small UAS (LAS) category as defined by a Civil Aviation Authority (CAA). Depending on the size and complexity of the sUAS, an AFM may also contain the instruction for maintenance and continuing airworthiness for owner / operator authorized maintenance.	ASTM F38 Unmanned Aircraft Systems		standard	published	published
Automatic modes, take Landing, taxir		WK58931 Evaluating AerialResponse RobotManeuvering: Maintain Position and Orientation	The purpose of this test method is to specify the apparatuses, procedures, and performance metrics necessary to quantitatively evaluate the system capability to accurately maintain position and orientation (pose) in open space relative to an object of interest. This test method applies to aerial systems operated remotely from a stander distance appropriate for the intended mission. The system includes a remote operator in control of all functionality and ray assistive features or autonomus behaviors that improve the effectiveness or efficiency of the overall system. This test method may be performed anywhere the specified apparatuses and environmental conditions can be implemented as described. Results should be considered within the context of related test methods in the Maneuvering suite when comprehensively evaluating robotic system capabilities.	ASTM E54 Homeland Security Applications	TBD	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
Automatic modes, take Landing, taxir		WK58932 Evaluating AerialResponse RobotManeuvering: Orbit a Point	The purpose of this test method is to specify the apparatuses, procedures, and performance metrics necessary to quantitatively evaluate the system capability to accurately orbit an object of interest. Results should be considered within the context of related test methods in the Maneuvering satile when comprehensively evaluating robotic system capabilities. This test method applies to aerial systems operated remotely from a standoff distance appropriate for the intended misson. The system includes a remote operator in control of all functionality and any assistive features or autonomous behaviors that improve the effectiveness or efficiency of the overall system. This test method may be performed anywhere the specified apparatuses and environmental conditions can be implemented as described.	ASTM E54 Homeland Security Applications	TBD	standard	ongoing	
Detect and av	bio	WK58933 Evaluating AerialResponse RobotManeuvering: Avoid Static Obstacles	The purpose of this test method is to specify the apparatuses, procedures, and performance metrics necessary to quantitatively evaluate the system capability to avoid static obstacles.	ASTM E54 Homeland Security Applications	TBD	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
Detect and a	roid	WK58934 Evaluating AerialResponse RobotManeuvering: Pass Through Openings	The purpose of this test method is to specify the apparatuses, procedures, and performance metrics necessary to quantitatively evaluate the system scapability to pass through openings of various sizes and orientations.	ASTM E54 Homeland Security Applications	TBD	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
Automatic modes, taker Landing, taxir	off,	WK58935 Evaluating AerialResponse RobotManeuvering: Land Accurately (Vertical)	The purpose of this test method is to specify the apparatuses, procedures, and performance metrics necessary to quantitatively evaluate the system capability to accurately land vertically within a defined area.	ASTM E54 Homeland Security Applications	TBD	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
UAS-ATM		Specifications for the Use of Military Unmanned Aerial Vehicles (UAV) as Operational Air Traffic (OAT) outside segregated airspace specification, v 1.0, 2007		EUROCONTROL		specification	published	
UAS-ATM		Air Traffic Management Guidelines for Global Hawk in European Airspace, v 1.0, 2010	These Guidelines establish a set of minimum ATM requirements for Global Hawk (GH) / Euro Hawk (EH) flight in European airspace, with the primary purpose of enabling GH/EH operators to use them as the basis for negotiating access to national airspace within Europe. The Guidelines envisage the isolation of GH/EH from other airspace users by requiring it to climb-out and recover in segregated airspace and to fly IFR/OAT in the cruise in non-segregated airspace at high altitudes that are above those occupied by manned aviation.	EUROCONTROL		guidance material	published	

Standard scenarios			ASTM F3196-18 Standard Practice for Seeking Approval for Extended Visual Line of Sight (EVLOS) or Beyond Visual Line of Sight (BVLOS) Small Unmanned Aircraft System (sUAS) Operations	Compliance with this practice is recommended as one means of seeking approval from a civil aviation authority (CAA) to operate a small unmanned aircraft system (sUAS) to fly extended visual line of sight (EVLCS) or beyone visual line of sight (EVLCS) or both. Any regulatory application of this practice to sUAS and other unmanned aircraft systems (UASs) is at the discretion of the appropriate CAA.	ASTM F38 Unmanned Aircraft Systems		standard	published	Body of standard revised and published incorporating Oathfinder results, appendix is pending. To be revised and ammended to include use case scenarios: package delivery, infrastructure inspection, linear inspection, search and rescue, emergency response, terminal operations, agriculture. First of these apendixes (package delivery) to be completed Jun 2018. Final available but revisions to standard will be incorporated in Jan 2018 after Pathfinder Technical Interchange.
Standard scenarios			ASTM WK 62344 BVLOS Package Delivery as an Appendix to F3196-17	Appendix to to ASTM F3196-17. The main purpose of this revision is to add an Appendix that can be used in developing proposed risk mitigation strategies for package delivery sUAS BVLOS operationsy	ASTM F38 Unmanned Aircraft Systems	Jun-19	standard	ongoing	Working group formed and continues
Operations			ASTM F2849-10 Standard Practice for Handling of Unmanned Aircraft Systems at Divert Airfields		ASTM F38 Unmanned Aircraft Systems		practice	published	
Operations			ISO 21384-3 - Requirements for safe civil RPAS/UAS operations and applies to all types, categories, classes, sizes and modes of operation of UAS	Requirements for safe commercial UAS operations and applies to all types, categories, classes, sizes and modes of operation of UAS.	ISO	Dec-18	standard	published	
UAS-ATM			ARP#### Access to controlled airspace		SAE G-30 UAS Operator Qualifications Committee	May-19	recommended practice	planned	
Standard scenarios			ARP#### Flight beyond visual line of sight		SAE G-30 UAS Operator Qualifications Committee	May-19	recommended practice	planned	
Standard scenarios			ARP#### Night operations		SAE G-30 UAS Operator Qualifications Committee	May-19	recommended practice	planned	
Standard scenarios			ARP#### Aerial photography		SAE G-30 UAS Operator Qualifications Committee	Jun-19	recommended practice	planned	
Standard scenarios			ARP#### Power line inspection		SAE G-30 UAS Operator Qualifications Committee	Jul-19	recommended practice	planned	
Standard scenarios			ARP#### Precision agriculture		SAE G-30 UAS Operator Qualifications Committee	Aug-19	recommended practice	planned	
Standard scenarios			ARP#### Bridge inspection		SAE G-30 UAS Operator Qualifications Committee	Sep-19	recommended practice	planned	
Standard scenarios			ARP#### Train right-of- way's		SAE G-30 UAS Operator Qualifications Committee	Oct-19	recommended practice	planned	
Standard scenarios			ARP#### Flare stack inspections		SAE G-30 UAS Operator Qualifications Committee	Nov-19	recommended practice	planned	
Standard scenarios			WK58243 New Guide fo Visual Inspection of Building Facade using Drone	This standard consists of guidelines for utilizing drones with cameras to document facade conditions with video and still photography. The purpose of this standard is to establish procedures and methodologies for conducting visual inspections of building facades via drone, and documenting such inspections.	ASTM E06 Performance of Buildings	f Jan-18	guide	ongoing	

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Navigation	WK59677 Evaluating AerialResponse RobotSensing: Visual Image Acuity	overall system. This test method may be performed anywhere the specified apparatuses and environmental conditions can be implemented as described. Results should be considered within the context of related test methods in the Maneuvering suite when comprehensively evaluating robotic system capabilities.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
Ground control station	WK58925 Evaluating AerialResponse RobotSensing: Visual Color Acuity	The purpose of this test method is to specify the apparatuses, procedures, and performance metrics necessary to quantitatively evaluate the visual (electro-optical) color acuity of the system as viewed through a control station.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
Ground control station	WK58926 Evaluating AerialResponse RobotSensing: Visual Dynamic Range	The purpose of this test method is to specify the apparatuses, procedures, and performance metrics necessary to quantitatively evaluate the visual (electro-optical) dynamic range of the system as viewed through a control station.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
C3 datalink and communication	WK58927 Evaluating AerialResponse RobotSensing: Audio Speech Acuity	The purpose of this test method is to specify the apparatuses, procedures, and performance metrics necessary to quantitatively evaluate the audio speech acuity of the system as heard bi-directionally between a control station and aerial robot in flight.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
Ground control station	WK58928 Evaluating AerialResponse RobotSensing: Therm Image Acuity	The purpose of this test method is to specify the apparatuses, procedures, and performance metrics necessary to quantitatively evaluate the thermal	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
Ground control station	WK58929 Evaluating AerialResponse RobotSensing: Therm Dynamic Range	The purpose of this test method is to specify the apparatuses, procedures, and performance metrics necessary to quantitatively evaluate the thermal dynamic range of the system as viewed through a control station.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
Ground control station	WK58930 Evaluating AerialResponse RobdSensing: Latenc of Video, Audio, and Control	The purpose of this test method is to specify the apparatuses, procedures, and performance metrics necessary to quantitatively evaluate the latency of video, audio, and control sub-systems as viewed through a control station.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
Detect and avoid	WK58936 Evaluating AerialRespoines RobotSituational Awareness: Identify Objects (Objects) Cameras)	The purpose of this test method is to specify the apparatuses, procedures, and performance metrics necessary to quantitatively evaluate the system capability to identify objects of interest in the environment using cameras om (electro-optical and thermal) from defined altitudes in open space.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
Standard scenarios	WK58937 Evaluating AerialResponse Robd/Situational Awareness: Inspect Static Objects	The purpose of this test method is to specify the apparatuses, procedures, and performance metrics necessary to quantitatively evaluate the system capability to inspect objects of interest in close proximity.	ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
Standard scenarios	WK58938 Evaluating AerialResponse RobotSituational Awareness: Map Wid Areas (Stitched Image		ASTM E54 Homeland Security Applications	Apr-18	standard	ongoing	E54 Full Committee adjudication February 26 to March 2, 2018. Delayed till Apr-18
Standard scenarios	ASTM WK52858 Sm Ummanned Aircraft Systems (sUASs) for Land Search and Res	search and rescue resources in terms of their capabilities. It provides a means by which resource managers and sUAS pilots/operators can convey to emergence the testing for which their customs are completed.	ASTM F32 Search and Rescue	TBD	standard	ongoing	
Standard scenarios	ASTM WK54226 sUA Operations in Search Rescue Operations		ASTM F32 Search and Rescue	TBD	standard	ongoing	
Standard scenarios	ASTM WK65042 New Specification for Operation over People	Patntinder studies. Using results of the Patntinder Program, impact testing	ASTM F38 Unmanned Aircraft Systems	Mar-19	specification	ongoing	Final draft for ballot in October 2018, adjudicating comments
UA Design and Airworthiness	ASTM F3389-20 Test Methods for Assessin the Safety of Small Unmanned aircraft System Impacts		ASTM F38 Unmanned Aircraft Systems		standard	published	
Risk Assessment	ASTM F3178-16 Standard Practice for Operational Risk Assessment of Small Ummanned Avcraft Systems (sUAS)	Preparation of an ORA in accordance with this practice is intended to reduce, the risk of an operation in which system complexity is minimal, the operation is conducted in a lower risk environment, and the likelihood for harm to people or property, though present, is reduced to an acceptable level. As mission complexity increases, the operational environment may become less risk tolerant. A.	ASTM F38 Unmanned Aircraft Systems		standard	published	This will be reference in AC for Special Class §21.17(b)
Manuals	ASTM WK60093S New Practice for General Operations Manual for Professional Operator Light Umanned Aircr Systems (UAS)	I his standard defines the requirements for General Operations Manual for Professional Operator of Light Unmanned Aircraft Systems (UAS). The standard addresses the requirements and/or best practices for	ASTM F38 Unmanned Aircraft Systems	Sep-18	specification	ongoing	Draft Complete - will be balloted Jun 2018

М	Take off/ Landing zones			F3423/F3423M-22 Standard Specification for Vertiport Design	To support the design of civil vertiports and vertistops for the landing and takeoff of VTOL aircraft boarding and discharging passengers or cargo. The proliferation of electric-powered VTOL should be carefully considered in the development of this document. The standard must be scalable to address aircraft ranging in size and kinetic energy, including unmanned and optionally piloted aircraft.	ASTM F38.02	Juil-22	specification	published	
	UAS-ATM			STANAG 7234 Remotely Piloted Aircraft Systems (RPAS) Airspace Integration (AI) AATMP-51		NATO FINAS	2018	standard	ongoing	Under development
	C3 datalink and communication			STANAG 7232 Unmanned Aerial Systems Tactics Techniques and Procedures - ATP- 3.3.8.2 Edition A	Provide standardized tactics, techniques, and procedures 217 for the planning, command and control (C2), and employment of unmanned aircraft systems 218 (UAS) in NATO operations	NATO MCASB/JCGUAS OS	2018	standard		
					This standard defines the requirements for General Operations Manual for Professional Operator of Light Unmanned Aircraft Systems (UAS). The standard addresses the requirements and/or best practices for documentation and organization of a professional operator (i.e., for compensation and hire). The intent is for this standard to support professional entities that will receive operator certification by a CAA, and provide standards of practice for self- or third-party audit of operators of UAS Not all CAAs have operator certificates. This would provide a standard for operators and identify gaps that are not currently addressed as it relates to: (1)Individuals, who are currently remote pilots (i.e. FAA under Part 107) in jurisdictions that do not separately certify Operators, who want to voluntarily comply with a higher standard, and (2)Operators, who are seeking certification from a CAA for Light Unmanned Aircraft Systems, who want to voluntarily comply with an industry standard (3)Public agencies interested in developing unmanned aircraft systems programs.	ASTM F38 Unmanned Aircraft Systems	Mar-19	standard	ongoing	Under development
				WK69335 Framework for Using ASTM Standards for UAS	This guide provides some major themes and examples for consideration related to compliance which are not necessarily captured in any single standard pertinent to UAS. The outline of this document is intended to loosely reflect the process that an organization would go through in order to reach and maintain production of UAS that is demonstrably compliant with the applicable Consensus-based standards. The guide describes the current standards and identifies gap areas to support umanned aircraft operations for commercial purposes. A CAA may, at their discretion, use this guide to aid the development of regulations. A commercial operator may, at their discretion, use this guide to aid their applications for regulatory approval; for example, when submitting a safety case as part of a Specific Operations Risk Assessment (SORA)	ASTM F38 Unmanned Aircraft Systems	Mar-19	guide	ongoing	
				prEN4709-4 Aerospace series - Unmanned Aircraft Systems (UAS) - Security requirements	This European standard will provide means of compliance to cover lighting related requirements for part 2 to 4 of the delegated act. The purpose is to be able to verify that an UA is equipped with lights which: ensure controllability of the UA sensure conspicuity of the aircraft at night, the design of the light shall allow a person on the ground to distinguish a UA from a manned aircraft. The standards will address: -Definition of types, technical requirements and technical parameters of UA lights (e.g. position of lights for different UA categories, intensity for different operation modes).	ASD-STAN D5WG8	Sep-21	preEN / European standard	published	
				ISO/NP 5015-1	Operational procedures for passenger-carrying UAS	ISO/TC 20/SC 16/WG 3	Nov-21	standard	ongoing	
				ISO/NP 5015-2	Operation of vertiports for unmanned aircraft (UA)	ISO/TC 20/SC 16/WG 3	Nov-20	standard	ongoing	
				ISO/WD 24354, ISO/WD 24355.	Payload interface for Small, Civil UAS Flight control system for Small Multirotor UAS	ISO/TC 20/SC 16 ISO/TC 20/SC 16	TBD TBD	standard standard	ongoing	
-				130/110 24300,	The Standard Specification must define Positioning Assurance and define	130/10/20/30/16	IDU	Standard	ongoing	
				ASTM WK75923 New Specification for Positioning Assurance, Navigation, and Time Synchronization for Unmanned Aircraft Systems	minimum requirements for the UAS to know where it is positioned (and potentially localized) and the error associated with that position. The Standard Specification must also define Navigation and define minimum requirements for UAS navigation. The Standard Specification must define Time Synchronization and define minimum requirements for the UAS to know that the time value that its systems are using is assured and trusted. While none of these essential functions are completely unique to BLOS operations, from a safety standpoint they become more critical for BVLOS/BLOS operations.	ASTM F38.02	Summer 2022	standard	ongoing	Title and description were changed in v7.0 based on a change proposal from ASTM
8				FC	CL					

Remote pilot competence	EU 2019/947	UAS.OPEN.20(4) be performed by a remote pilot: (a) familiarised with the user's manual provided by the manufacturer of the UAS; (b) in the case of an unmanned aircraft class C1, as defined in Part 2 of the Annex to Delegated Regulation (EU) [20190306-021], who has completed an online training course followed by completing successfully an online theoretical knowledge examination provided by the competent authority or by an entity recognised by the competent authority or by an entity recognised by the competent authority of the Member State of registration of the UAS operator. The examination shall comprise 40 multiple-choice questions distributed appropriately across the following subjects: i. air safety; ii. air safety; iii. air safety; iv. thuman performance limitations; iv. human performance limitations; iv. UAS general knowledge; ivii. privary and data protection; iviii. insurance; ivii. insurance; ivii. insurance; ivii. insurance;	EASA	Jun-19	open and specific	Regulation applicable from 1 July 2020							
							ISO 23665 - Unmanned aircraft systems Training for personnel involved in UAS operations	The purpose of this international standard is that the persons who work for UAS operation receive appropriate education and obtain required knowledge and skill. Persons or educational organizations qualified according to this standard will be internationally regarded. It will enhance international operation of UAS, personal exchange and international trade.	ISO/TC 20/SC 16/WG 3	Oct-20	Standard	published	
Remote pilot competence							ARP5707 - Pilot Training Recommendations for Unmanned Aircraft Systems (UAS) Civil Operations	This document provides an approach to the development of training topics for pilots of Unmanned Aircraft Systems (UAS) for use by operators, manufacturers, and regulators. The identification of training topics is based nitially on Practical Test Standard (PTS) topics for manned aircraft pilots. The topics identified could be used for the construction of a PTS for UAS commercial pilot operations and a PTS for a UAS pilot instrument rating. The UAS commercial pilot rating would contain restrictions on the types of operations that could be flown that would be dependent on the type of UAS used. The UAS type would also influence the specific training topics that would be covered. This document is not intended to utiline the requirements for other crewmembers, such as observers, payload operators, or ground personnel, nor does it distinguish between different levels of pilot authority or discuss the roles for pilot-in-command, supplemental pilot, or observer.	SAE G-30 UAS Operator Qualifications Committee & G- 10U Unmanned Aerospace Vehicle Committee		recommended practice	published	
Remote pilot competence							ARP#### Common operator qualifications		SAE G-30 UAS Operator Qualifications Committee	May-19	recommended practice	planned	
Remote pilot competence	EU 2019/947	UAS.OPEN.030(2) be performed by a remote pilot who is familiar with the user's manual provided by the manufacturer of the UAS and holds a certificate of remote pilot competency issued by the competent authority or by an entity recognised by the competent authority or by an entity recognised by the competent authority or the Member State of registration of the UAS operator. This certificate shall be obtained after complying with all of the following conditions and in the order indicated: (a) completing an online training course and passed the online theoretical knowledge examination as referred to in point (4)(b) of point UAS.OPEN.020; (b) completing a self-practical training in the operating conditions of the subcategory A3 set out in points (1) and (2) of point UAS.OPEN.020; (c) declaring the completion of the self-practical training defined in point (b) and passing an additional theoretical knowledge examination provided by the competent authority or by an entity recognised by the competent authority of the Member State of registration of the UAS operator. The examination shall comprise at least 30 multiple-choice questions aimed at sassessing the remote pilot's knowledge of the technical and operational mitigations for ground risk, distributed appropriately across the following subjects: i. meteorology. ii. UAS flight performance; iii. technical and operational mitigations for ground risk.	EASA	Jun-19	open and specific	Regulation applicable from 1 July 2020							
maintenance							ASTM WK76061 New Guide for Lightweight UAS Maintenance Technician Qualification	The purpose of this guide is to address the basic fundamental subject knowledge, task performance, and task knowledge activities and functions for UAS maintenance professionals to be titled UAS Maintenance Technicians	ASTM F38 Unmanned Aircraft Systems and F46 Aerospace Personnel	Jun-18	standard	ongoing	Undergoing revisions prior to ballot
Remote pilot competence							F3379-20 Guide for training Public Safety Remote of Unmanned Aircraft Systems Endorsement	To develop a standard that defines the requirements for Training for Public Safety Remote Pilot of Unmanned Aircraft Systems (UAS) Endorsement. The guide describes the knowledge, skills, and abilities required to operate unmanned aircraft for public safety purposes. A CAA may, at their discretion use this guide to ad the development of regulations. An approved ASTM guide that describes required education, training, and continuing professional development for those performing as professional public safety remote pilot.	ASTM F38 Unmanned Aircraft Systems		standard	published	

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									Establish criteria for Training and Certification of sUAS Pilots, Instructors, and School Houses. This program defines the knowledge skills and challings					
	Remote pilot competence							ASTM F3266 Standard Guide for Training for Remote Pilot in Command of Unmanned Aircraft Systems (UAS) Endorsement		ASTM F38 Unmanned Aircraft Systems	Apr-18	standard	published	
								ASTM WK61763 Training for Remote Pilot Instructor (RPI) of Unmanned Aircraft Systems (UAS) Endorsement	Endorsement. The guide describes the knowledge, skills, and abilities required to safely instruct remote pilots to operate unmanned aircraft for commercial purposes. A CAA may, at their discretion, use this guide to aid the development of regulations	ASTM F38 Unmanned Aircraft Systems	Jul-19	standard	ongoing	
									1.1 This specification defines the requirements for training and the development of training manuals for the unmanned aircraft systems (UAS) operator. 1.2 This specification addresses the requirements or best practices or both for documentation and organization of a professional operator (that for compensation and hire). 1.3 This specification supports professional entities that will receive operator certification by a civil aviation authority (CAA) and provide standards of practice for self- or third-party audit of operators or GIUAS. 1.4 The case study used to develop this specification focused on operators of light UAS (below 120) Blo60 kg as defined by EASA), but this specification may be applied to larger aircraft for using other methods of classification (that is, risk-based classes and pilot privileges classes). 1.5 Training manuals that do not include all the minimum requirements of this specification may not be referred to as meeting this specification.		Sep-19	standard	ongoing	
	Remote pilot competence							ASTM F3330-18 Standard Specification for Training and the Development of Training Manuals for the UAS Operator	This specification defines the requirements for training and the development of training manuals for the unmanned aircraft systems (UAS) operator.	ASTM F38 Unmanned Aircraft Systems	Nov-19	standard	publihed	
	Remote pilot competence							ARP5707 Pilot Training Recommendations for Unmanned Aircraft Systems (UAS) Civil Operations	1.2 The specification addresses the requirements or best practices, or both, for documentation and organization of a professional operator (that is, for compensation and hire) for the purposes of internal training programs and for programs offered to the general public.	G-30 UAS Operator Qualifications Committee & G- 10U Unmanned Aerospace Vehicle Committee		recommended practice	published	
	Remote pilot competence							STANAG 7192 Ed: 1 Principles Underpinning Medical Standards for Operators of Unmanned Aerial Systems (UAS) - AAMedP-1.25, Edition A	Highlight the medical factors involved in the medical aspects of Flight Crew Licensing to enable individual nations to further their own medical standards for safe UAS operation.	NATO		standard	published	
	Remote pilot competence	EASA Decision	OSO #09 - Remote crew trained and current and able to control the abnormal and emergency situations (i.e. Technical issue with the IJAS)	EASA	Oct-19	Specific	published							
C	Remote pilot competence	EASA Decision	OSO #15 - Remote crew trained and current and able to control the abnormal and emergency situations (i.e. Human Error)	EASA	Oct-19	Specific	published							
CI	Remote pilot competence	EASA Decision	OSO #22 - The remote crew is trained to identify critical environmental conditions and to avoid them	EASA	Oct-19	Specific	published							
c	Remote pilot competence	EASA Decision	OSO#16 Multi crew coordination. (Criterion #2 Training)	EASA	Oct-19	Specific	published							
c	Remote pilot competence	EASA Decision	OSO#17 Remote crew is fit for the operation	EASA	Oct-19	Specific	published							
C	Remote pilot competence		OSO#19 Safe recovery from Human Error (Criterion #2 Training)	EASA	Oct-19	Specific	published							
	Remote pilot competence	EASA Decision	OSO#23 Environmental conditions for safe operations defined, measurable and adhered to (Criterion #1 Procedures)	EASA	Oct-19	Specific	published							
	Remote pilot competence	EASA Decision	M#1 An Emergency Response Plan (ERP) is in place, operator validated and effective (<u>Criterion #2 Remote Crew Competences</u>)	EASA	Oct-19	Specific	published							
								WK73142 Weather Supplemental Data Service Provider (SDSP) Performance	Management (UTM) ecosystem.	Aircrait Systems		standard	ongoing	
								WK62741 Training UAS Visual Observers	for visual observers of unmanned aircraft systems operations.	ASTM F38 Unmanned Aircraft Systems	Mar-19	guidance material	ongoing	
								ISO/WD 4358 ISO/WD TR 4595	Test methods for civil multi-rotor unmanned aircraft system Suggestion for improvement in the guideline for UA testing			standard standard	ongoing	
							-	ISO/WD TR 4595	classification			standard		
								ISO/WD TR 4594 ISO/WD TR 4584	UA wind gust test Improvement in the guideline for UA testing/design			standard standard	ongoing ongoing	
								ISO/WD 5109	Evaluation method for the resonance frequency of multi-copter UA			standard	ongoing	
								ISO/WD 5110 ISO/WD TR 5337	Test method for flight stability of multi-rotor UA Environmental Engineering Program Guideline for UA			standard standard	ongoing	
													ongoing	

	Noise&Environm ent	EU 2019/945	Parts 2(8) and 3(10) UAS in class C1 and C2 shall have, unless it is a fixed-wing UA, a guaranteed A-weighted sound power level LWA determined as per Part 13 not exceeding the levels established in Part 15	EASA	Jun-19	open	Regulation applicable	Product and Verification Requirements	technical requirements and covers, but is not limited to, physical and mechanical properties, flarmability, electrical properties, flurmability, electrical properties, flurmability, estoriator, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
10								Autonomou	s operations					
	Autonomous operations							AS6386 JAUS Autonomous Behaviors Service Set	This document, the JAUS Automated Behaviors and Diagnostics Service Set, defines a message-passing interface for services commonly found in mobile unmanned systems. These services represent the platform- independent capabilities common across all domains. Additional capabilities are specified in the JAUS Core Service Set (ASS710) and are frequently referenced herein.	SAE AS-4JAUS Joint Architecture for Unmanned Systems Committee	May-19	standard	ongoing	
	Autonomous operations							ASTM Aviation Autonomy Roadmap	Task group to matix autonomy technologies and standards between manned and unammned aircraft.	ASTM	TBD	standards and practices	ongoing	Task Group Formed
	Development assurance (Software)							ASTM F3269 Standard Practice for Methods to Safely Bound Flight Behavior of Unmanned Aircraft Systems Containing Complex Functions	aviation authority (CAA) that the light behavior of an unmanned aircraft system (UAS) containing complex function(s) is constrained through a run- time assurance (RTA) architecture to maintain an acceptable level of flight safety.	ASTM F38 Unmanned Aircraft Systems		standard	published	
	Autonomous operations							AS8024 JAUS Autonomous Behaviors Service Set	This document, the JAUS Automated Behaviors and Diagnostics Service Set, defines a message-passing interface for services commonly found in mobile unmanned systems. These services represent the platform- independent capabilities common across all domains. Additional capabilities are specified in the JAUS Core Service Set (ASS710) and are frequently referenced herein.	SAE AS-4JAUS Joint Architecture for Unmanned Systems Committee	May-19	standard	ongoing	The title will change to "JAUS Autonomous Capabilities Service Set"
	Noise&Environm ent	EU 2019/945	Parts 2(9) and 3(11) UAS in class C1 and C2 shall have, unless it is a fixed-wing UA, the indication of the guaranteed A-weighted sound power level affixed on the UA and/or its packaging as per Part 14;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the Open Taggory (class CO, C1, C2, C3 and C4 UAS). This document does not cover "Specific" or Certified" category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, but is not limited to, physical and mechanical properties, flammability, efectional properties, functional safety, software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
	Noise&Environm ent	EU 2019/945	Part 4(6) UAS in class C3 shall have, unless it is a fixed-wing UA, the indication of the guaranteed A-weighted sound power level LWA determined as per Part 13 affixed on the UA and/or its packaging as per Part 14;	EASA	Jun-19	open	Regulation applicable	prEN4709-1 Aerospace series - Unmanned Aircraft Systems (UAS) - Product and Verification Requirements	This European standard will provide means of compliance to cover Part 1 to 5 of the delegated act annex. This includes compliance with product requirements for all UAS authorized to operate in the 'open' category (class C0, C1, C2, C3 and C4 UAS). This document does not cover "Specific" or "Certified" category of UAS. Compliance with this document assists in complying with CE marking technical requirements and covers, bit is not limited to, physical and mechanical properties, flammability, electrical properties, floring software, readability of the instructions and manual etc. Additional hazards that occur from the characteristics of third party payloads are excluded.	ASD-STAN D5WG8	Dec-24	preEN / European standard	Published	
11								SC Lig	ht-UAS					
								EUROCAE Document	ED-80 Design Assurance Guidance for Airborne Electronic Hardware	EUROCAE	Apr-00	standard	published	Added to RDP as standard was recommended by AW- Drones
								EUROCAE Document	ED-12C Software Considerations in Airborne Systems and Equipment Certification	EUROCAE	Issued in January 2012 (incl. Corrigendum 1 released in February 2021)	standard	published	Added to RDP as standard was recommended by AW-Drones
								ASTM F44	ASTM F3367-21 Simplified High Intensity Radiated Field (HIRF) Protection in Level 1 and Level 2 Aircraft	ASTM	May-2021	standard	published	Added to RDP as standard was recommended by AW- Drones
								ASTM F44	ASTM F3309 - Standard Practice for Simplified Safety Assessment of Systems and Equipment in Small Aircraft	ASTM	published	standard	published	Added to RDP as standard was recommended by AW- Drones
								IEC TC 21/SC 21A - Secondary cells and batteries containing alkaline or other non-acid electrolytes	IEC 62133:2017 Secondary cells and batteries containing alkaline or other non-acid electrolytes - Safety requirements for portable sealed secondary cells, and for batteries made from them, for use in portable applications	IEC	Jul-21	standard	published	Added to RDP as standard was recommended by AW-Drones